

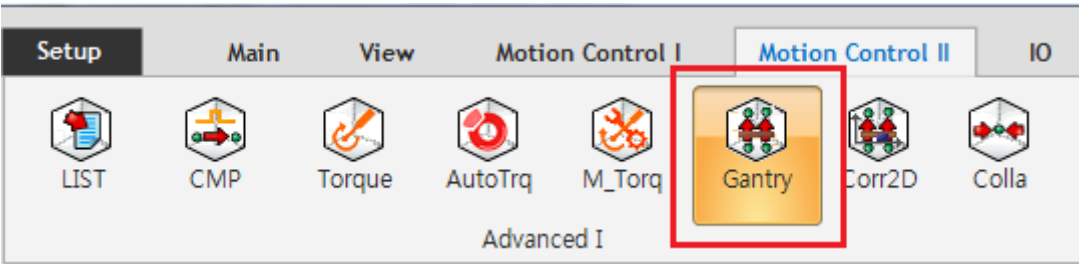
.....	1
.....	1
.....	2
.....	3

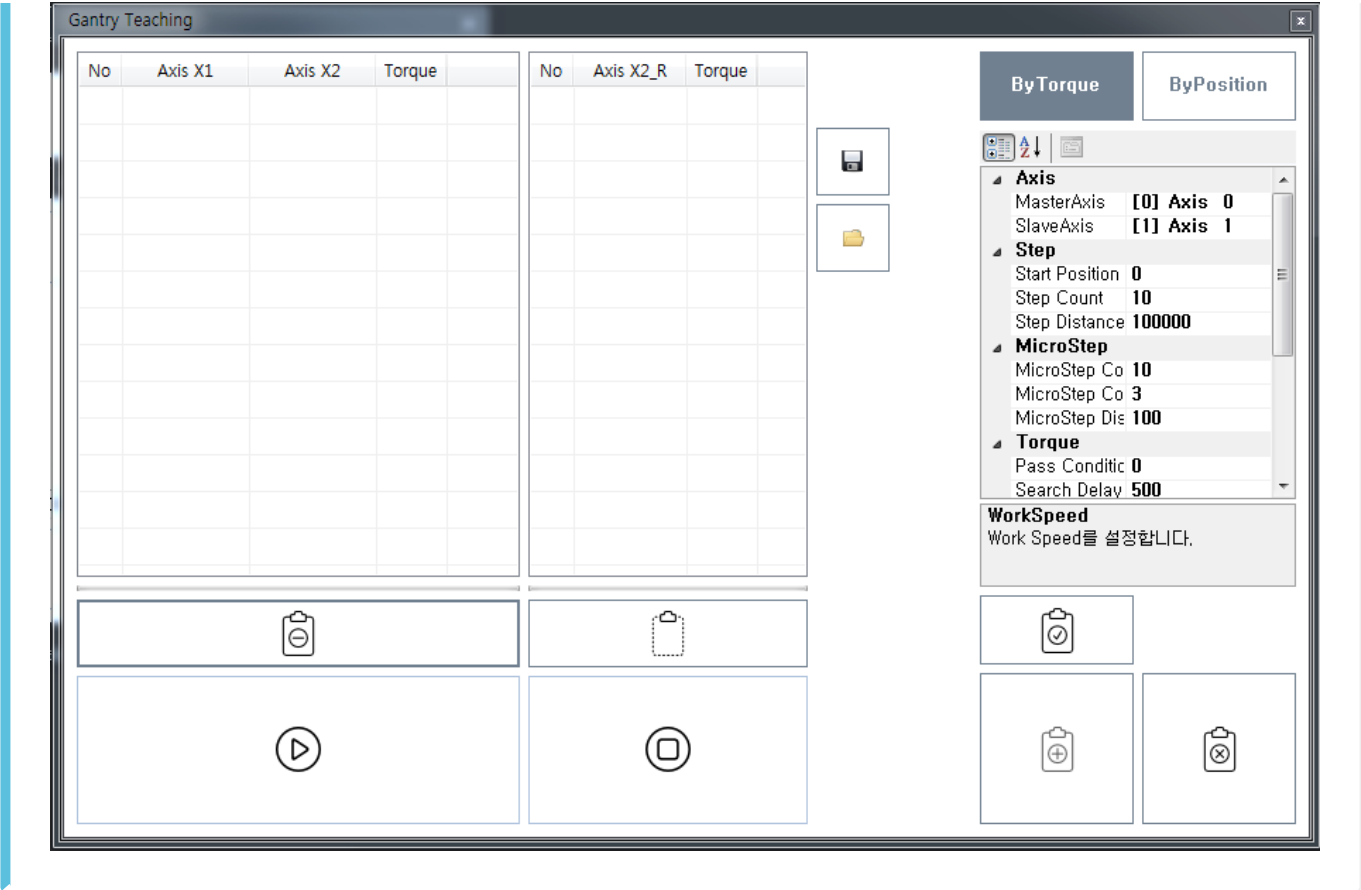
Gantry Teaching

x

- Master Slave , Step Distance MicroStep Distance .
- Gantry Step Distance , MicroStep , 가 가 .
- 가 Master Slave 가 .
- Step Count table .
- Table , Master-Slave Master , Slave 가 .
- Table
 - (1000, 990), (2000, 994) , 가 1500 , Slave 992

- ComilDE Gantry Gantry Teaching .





Axis

- Master Axis : Gantry Master
- SlaveAxis : Gantry Slave

Step

- Start Position : Teaching
 - Start Position 0
- Step Count, Step Distance :
 - Step Count , Step Distance , StepCount *
 - StepDistance 가 , Step Count = 10, Step Distance = 100 , 1,000

MicroStep

- MicroStep Count :
 - + / - MicroStep Count , Step
 - MicroStep Count
- MicroStep CountLimit : MicroStep Torque가 CountLimit 가
 - , CountLimit = 3 1,2,3 1.2, 2.1, 2.5 , 가
 - , + -
- MicroStep Distance : MicroStep 가

Torque

- Pass Condition : Pass Condition 가 , Step

-- http://comizoa.co.kr/info/

- Search Delay : Micro Step Delay .
- Torque Limit : , .
- Torque Warning : , Warning

The screenshot displays the 'Gantry Teaching' software interface. It features two data tables, a set of control buttons, and a parameter settings panel on the right.

Table 1 (Left):

No	Axis 0	Axis 1	Torque
0	0	-300	1
1	20000	19800	0,8
2	40000	39800	0,2
3	60000	59800	0,6
4	80000	79900	1,6
5	100000	99900	1,1
6	120000	119900	1,1
7	140000	139900	1
8	160000	159900	0,8
9	180000	179900	0,3
10	200000	199900	2

Table 2 (Right):

No	Axis 1	Torque
0	0	13,7
1	100	36,9
2	200	40,8
3	300	45
4	-100	6
5	-200	2,4
6	-300	1
7	-400	5
8	-500	7,3
9	-600	9,8

Control Buttons:

- Top row: Stop (red square), Home (house icon), Run (play button), and a square button.
- Bottom row: Four clipboard icons with different symbols (minus, plus, square, and cross).

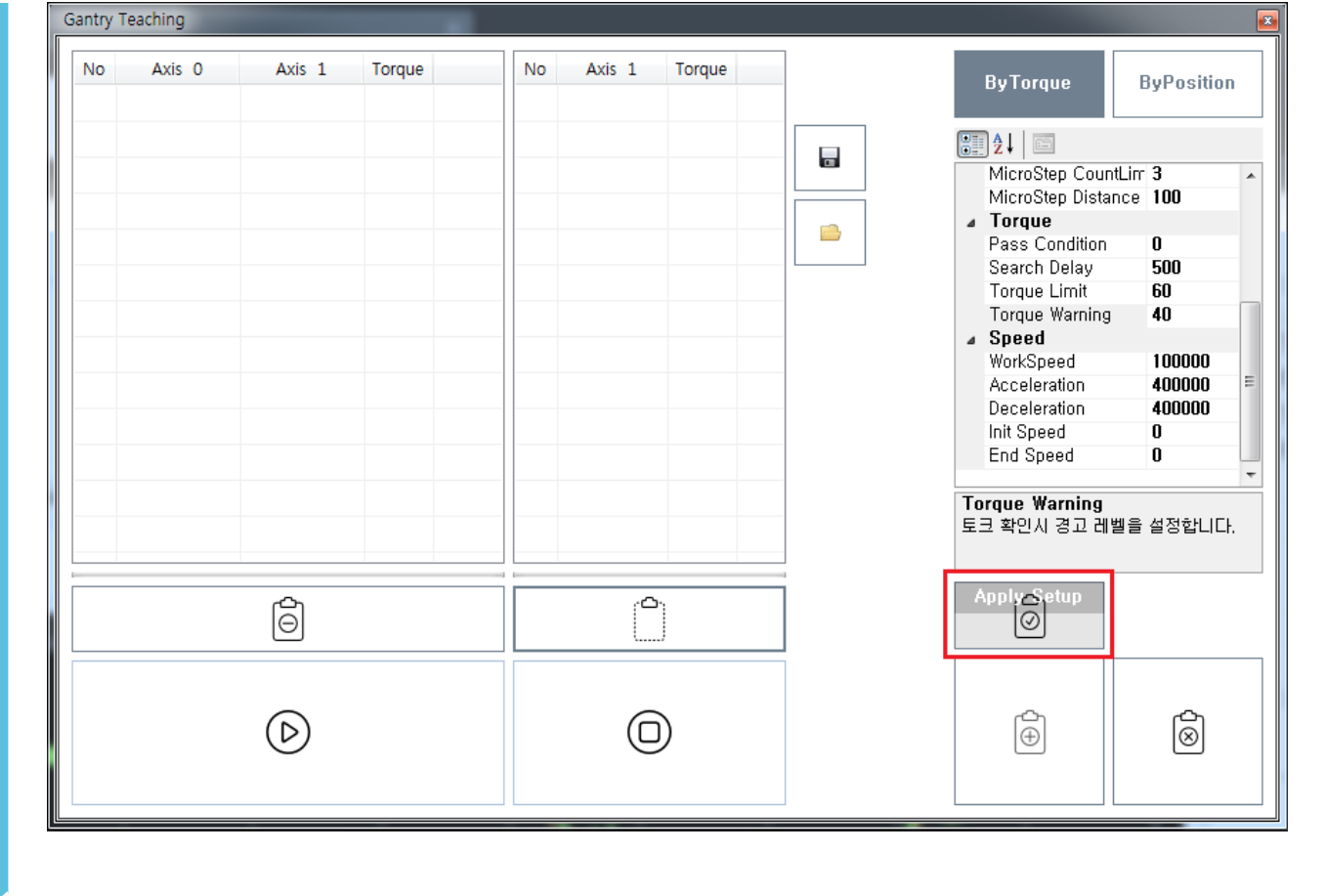
Parameter Settings Panel (Right):

- ByTorque** / **ByPosition** tabs.
- Step** section: Start Position (0), Step Count (10), Step Distance (20000).
- MicroStep** section: MicroStep Count (10), MicroStep CountLim (3), MicroStep Distance (100).
- Torque** section: Pass Condition (0), Search Delay (500), Torque Limit (60), **Torque Warning (40)** (highlighted).
- Speed** section: **Torque Warning** (highlighted) with text '토크 확인시 경고 레벨을 설정합니다.'

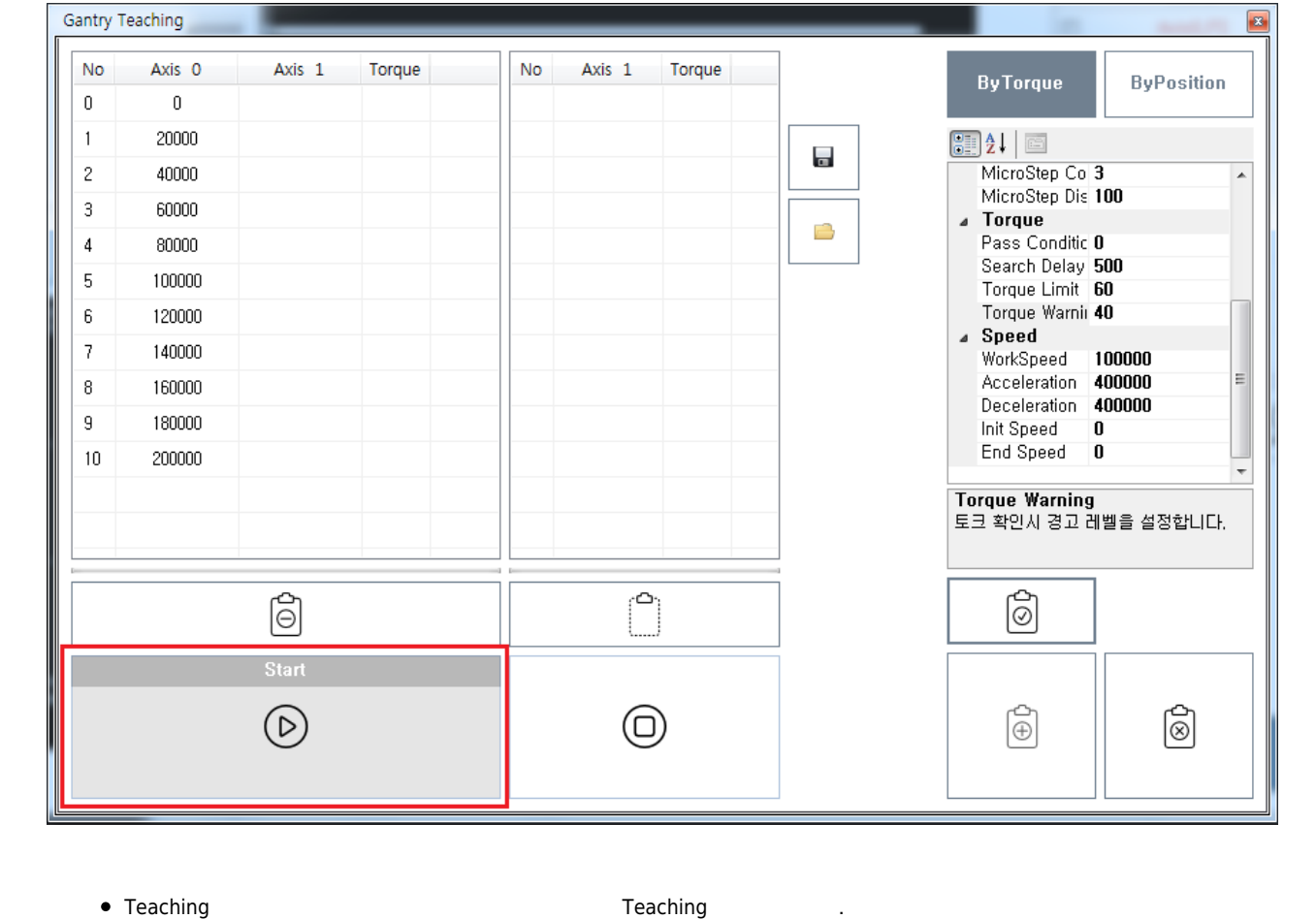
Speed

- Teaching

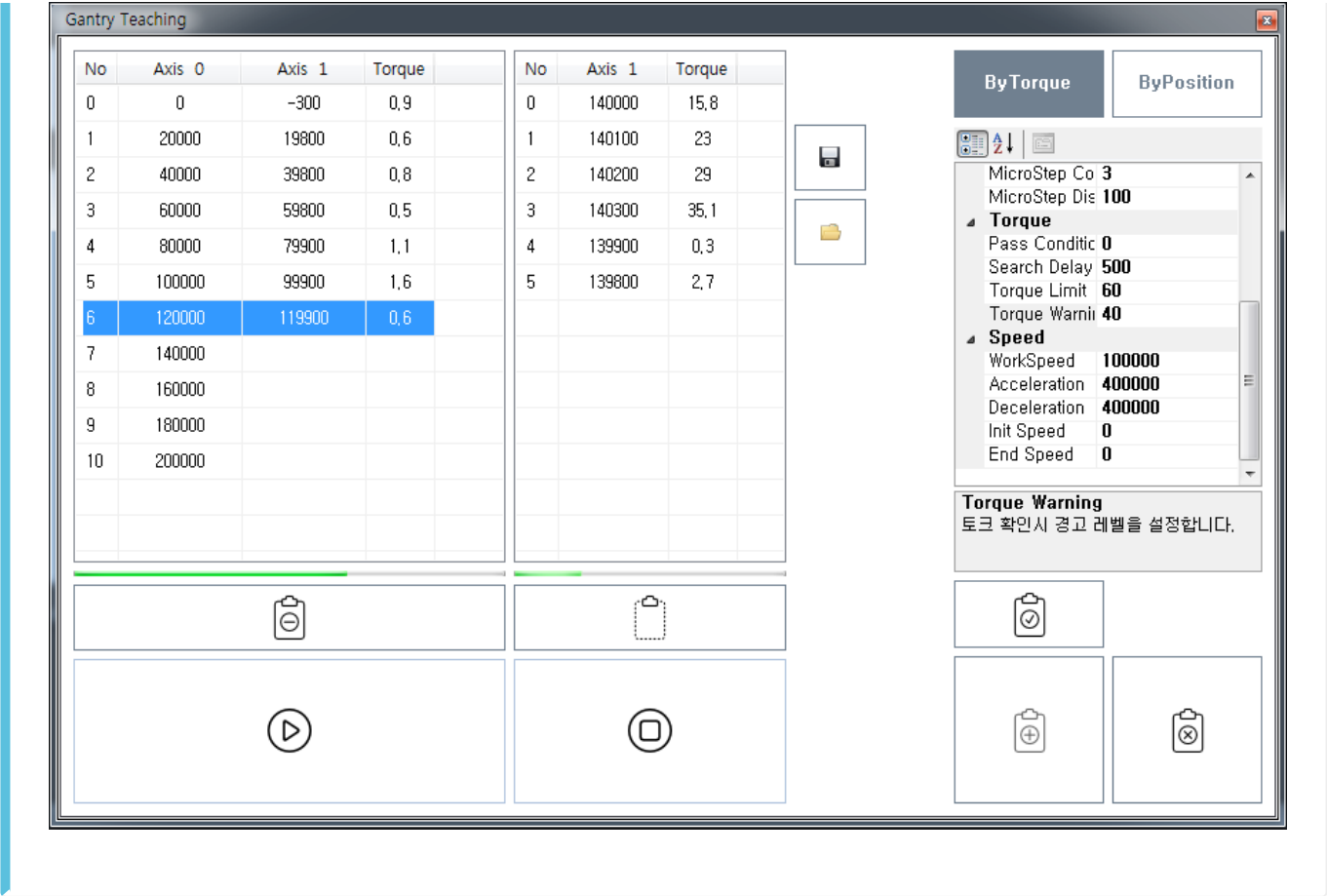
- ApplySetup



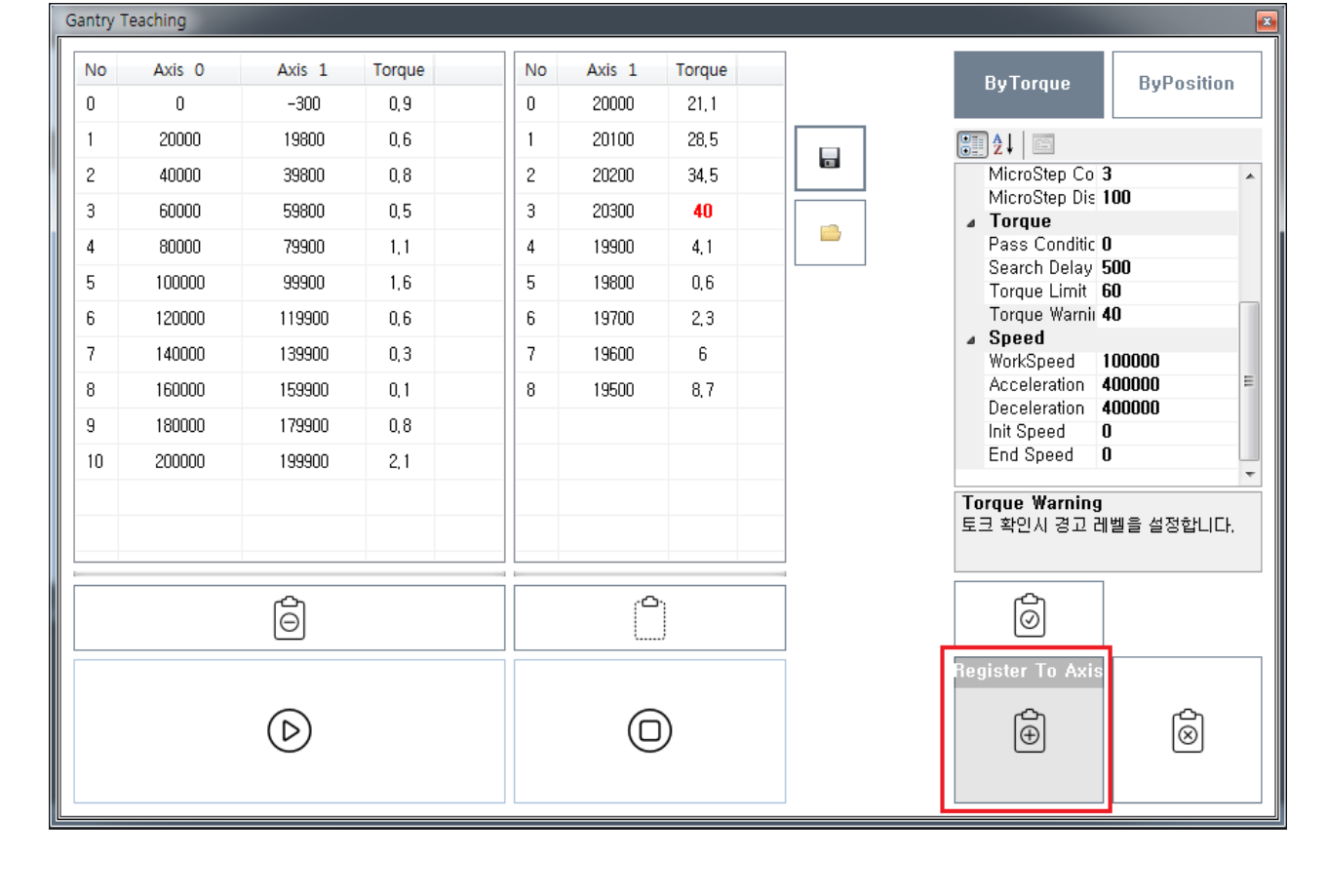
• Start Teaching



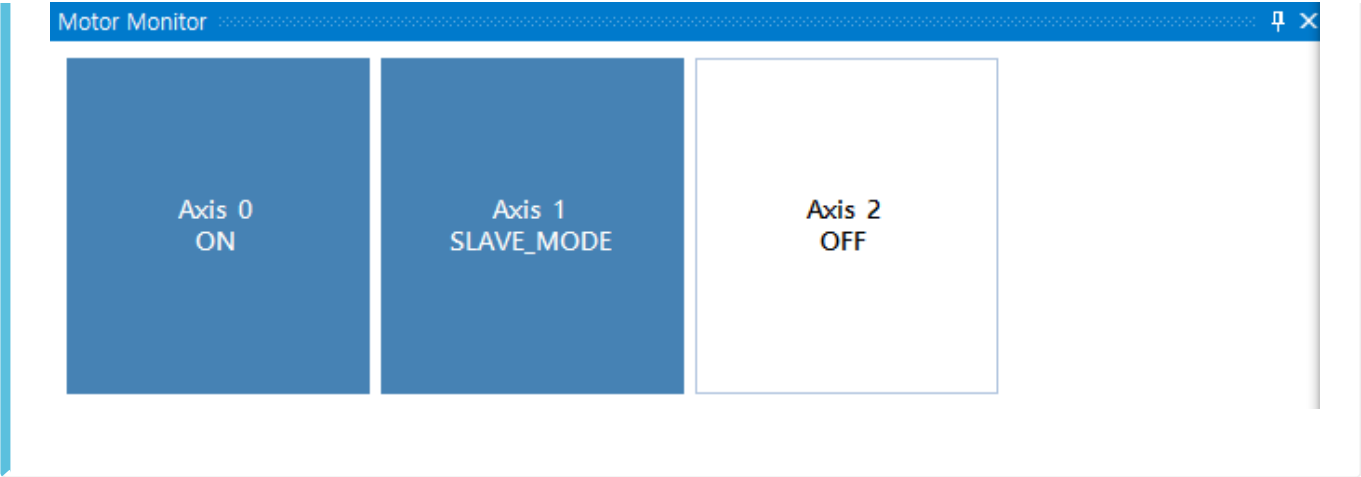
• Teaching Teaching



- Teaching Register To Axis



- , Master-Slave



• Step Step MicroStep .

Gantry Teaching

No	Axis 0	Axis 1	Torque
0	0	-300	0,9
1	20000	19800	0,6
2	40000	39800	0,8
3	60000	59800	0,5
4	80000	79900	1,1
5	100000	99900	1,6
6	120000	119900	0,6
7	140000	139900	0,3
8	160000	159900	0,1
9	180000	179900	0,8
10	200000	199900	2,1

No	Axis 1	Torque
0	20000	21,1
1	20100	28,5
2	20200	34,5
3	20300	40
4	19900	4,1
5	19800	0,6
6	19700	2,3
7	19600	6
8	19500	8,7

ByTorqueByPosition

MicroStep Co 3

MicroStep Dis 100

Torque

Pass Conditio 0

Search Delay 500

Torque Limit 60

Torque Warnin 40

Speed

WorkSpeed 100000

Acceleration 400000

Deceleration 400000

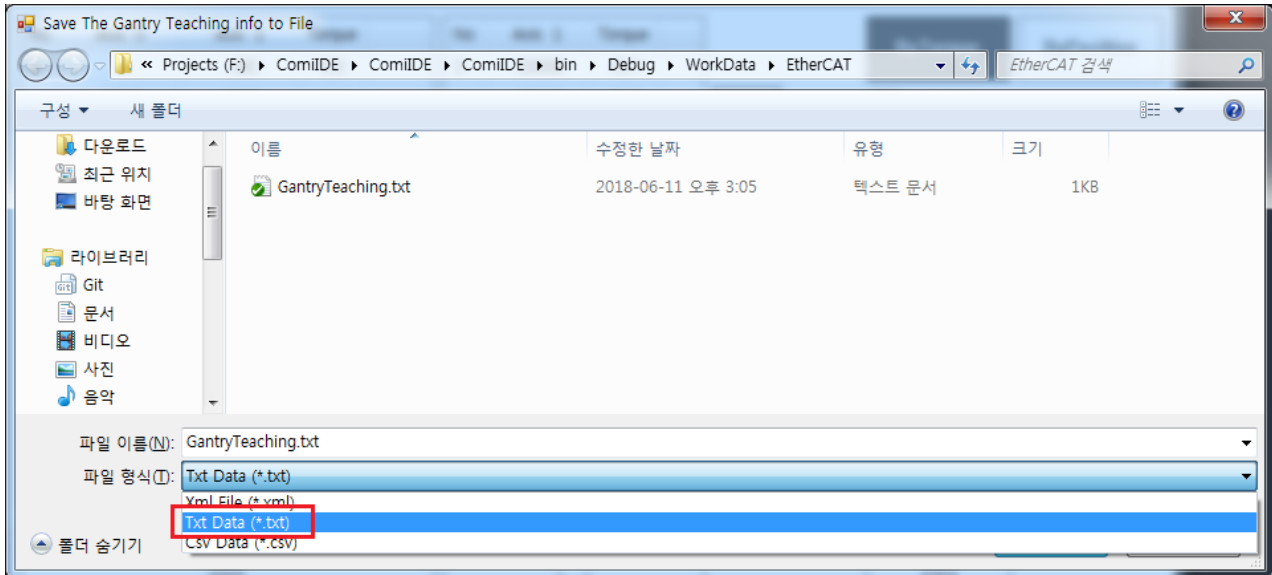
Init Speed 0

End Speed 0

Torque Warning

토크 확인시 경고 레벨을 설정합니다.

• Save txt UserApplication API .



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