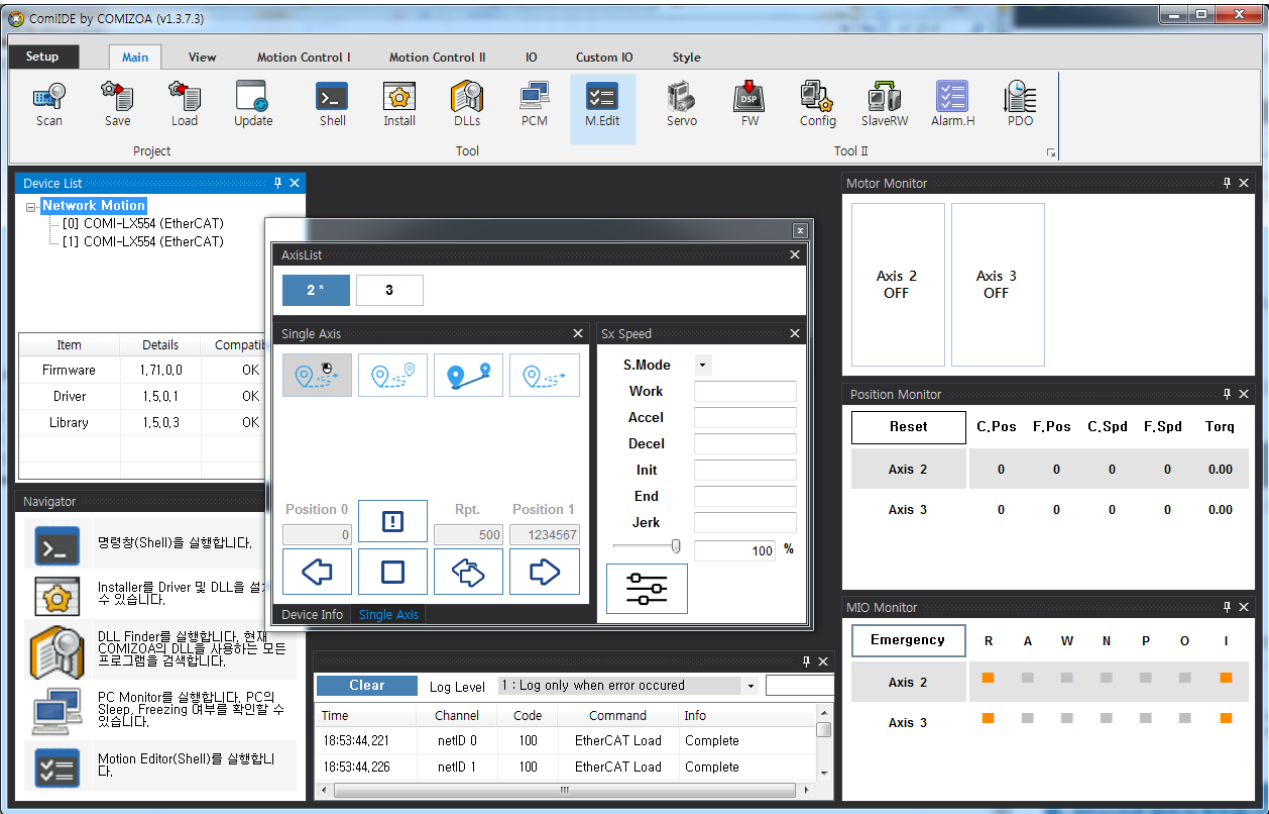


	1
	2
Servo On	3
Motor State	3
	4
	5
	7
	9

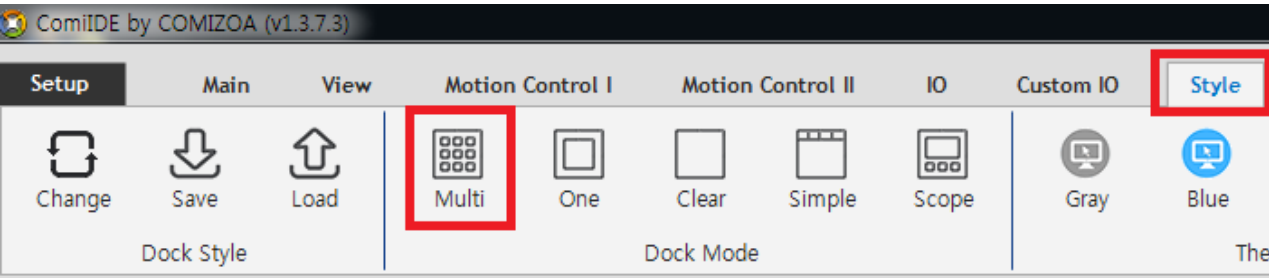
Motion Test

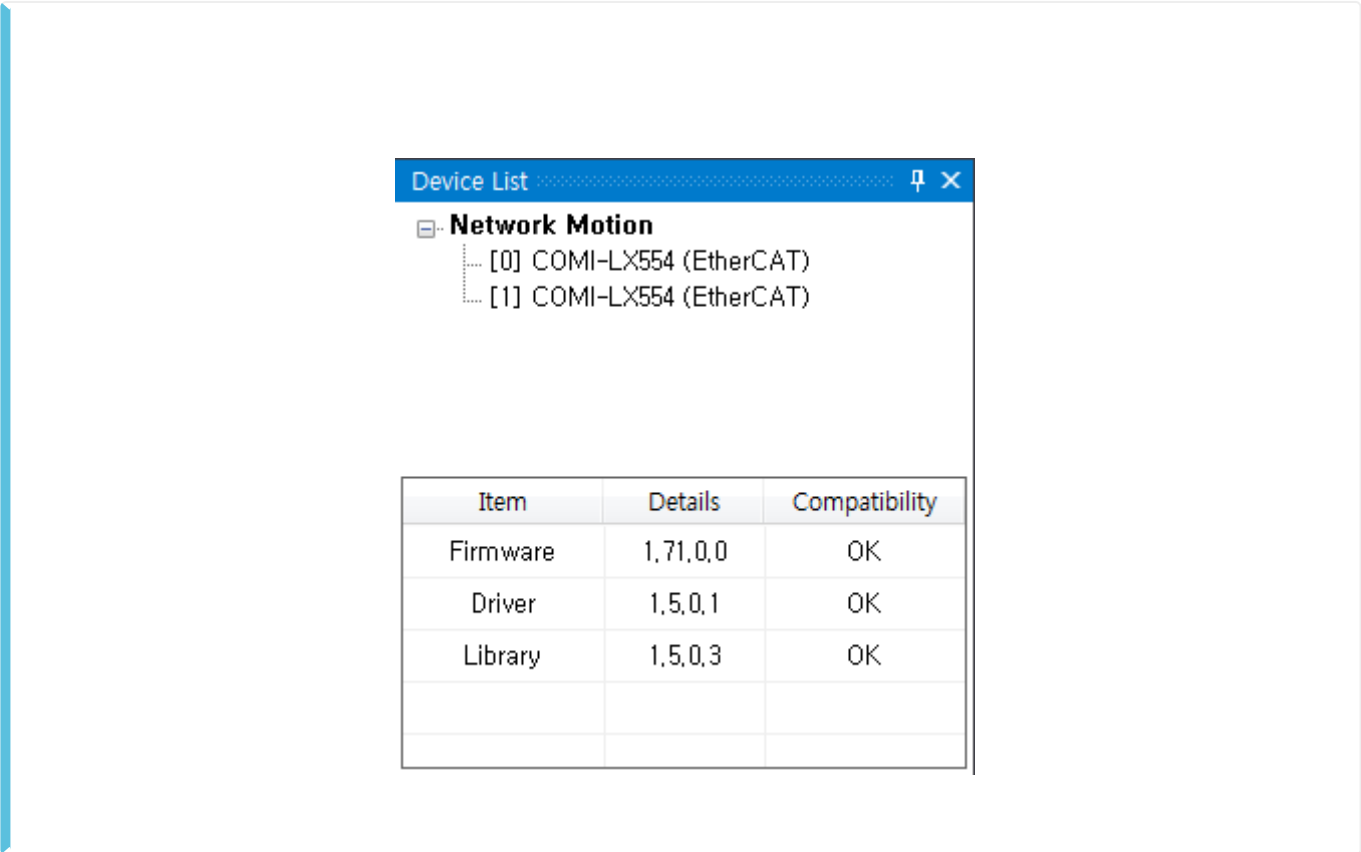
× ComiIDE

- ComiIDE



- , Style - Multi





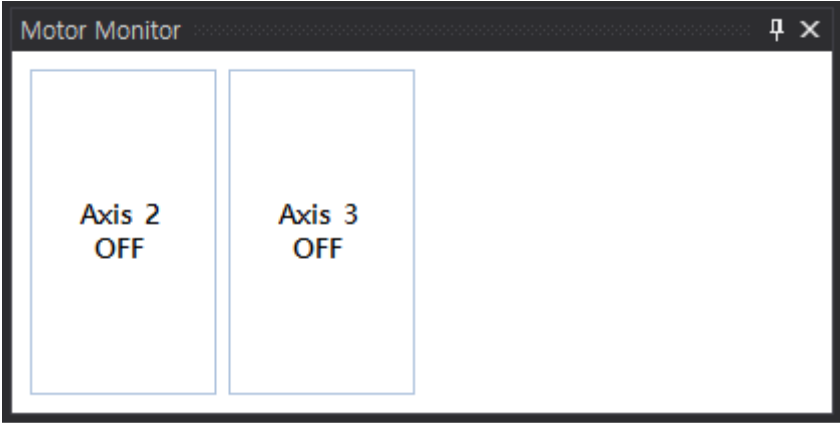
- DeviceList , Load .
- Device가 , .

Clear		Log Level		1 : Log only when error occurred		Find
Time	Channel	Code	Command	Info		
23:21:32,750	netID 0	100	EtherCAT Load	Complete		
23:21:32,773	netID 1	100	EtherCAT Load	Complete		

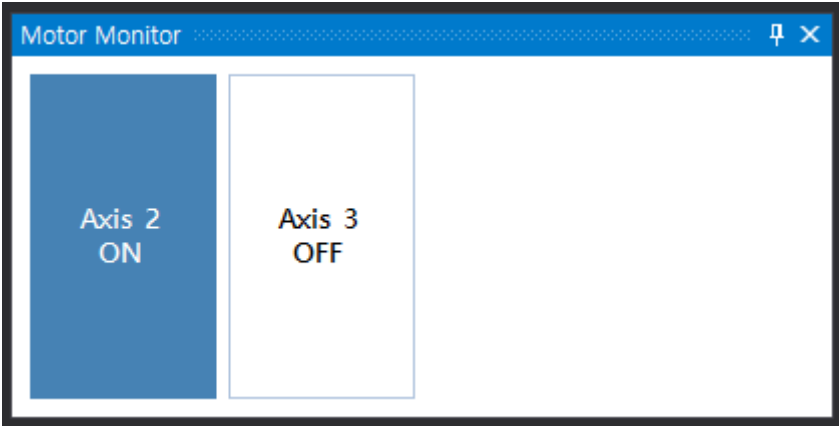
- LogView Load 가 .
- LogView **Log View** .

Servo On

- Motor Monitor 가 .



- Servo_On .



- Motor Monitor Motor . ServoOn Stop .
- Motor Monitor **Motor Monitor** .

Motor State

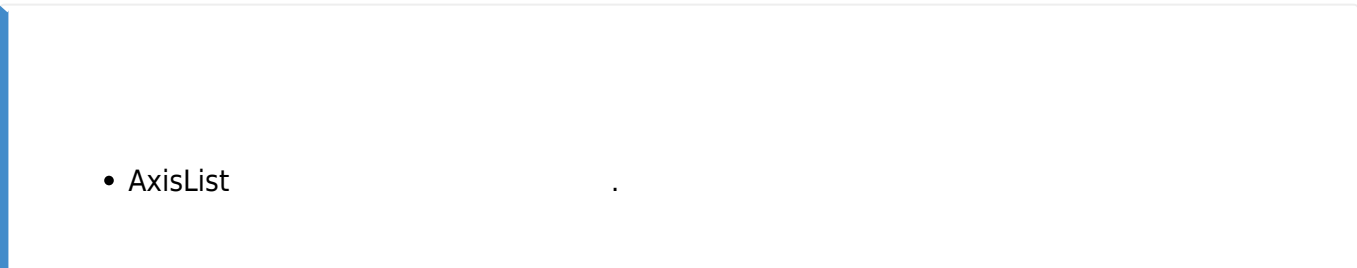
- Motor가 , .



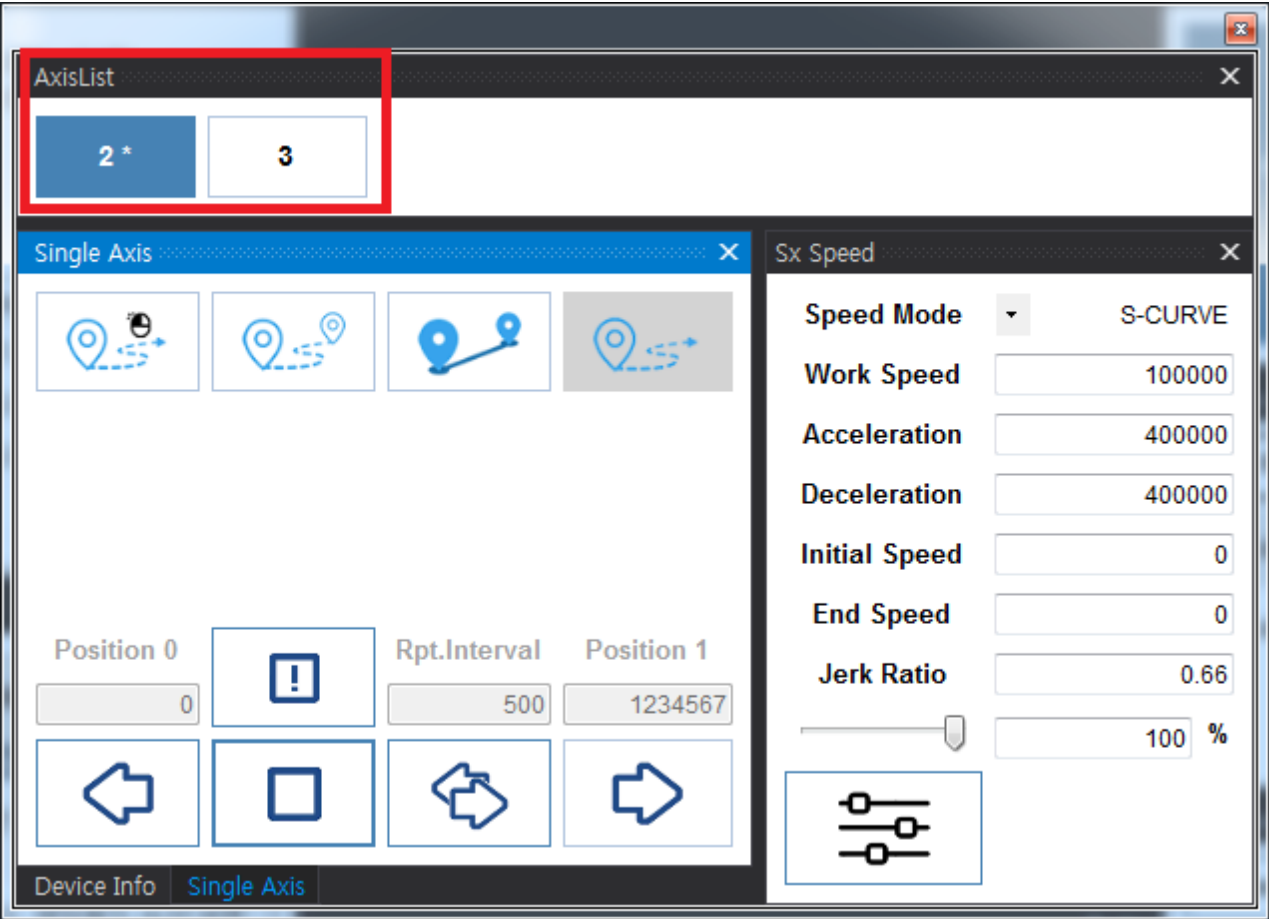
- Motor 가 Alarm , 가
- , Servo-On .
- MIO Monitor Motor가 가 .

MIO Monitor							
Emergency	RDY	ALM	WARN	NEL	PEL	ORG	INP
Axis 2							
Axis 3							

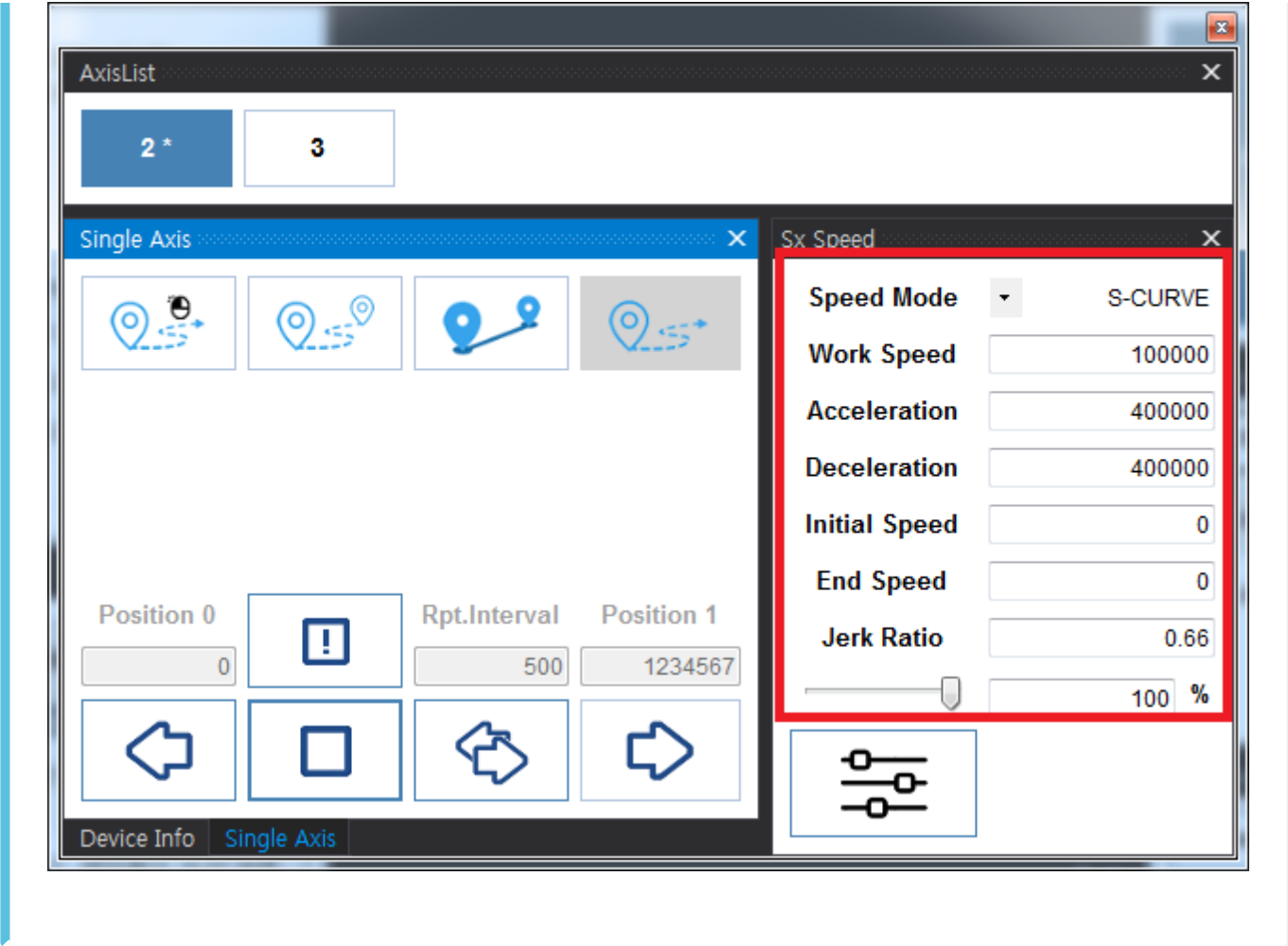
- , Alarm , PEL (Limit+) / NEL(Limit-) 가
- Ready , RDY 가 .
- MIO Monitor **MIO Monitor** .



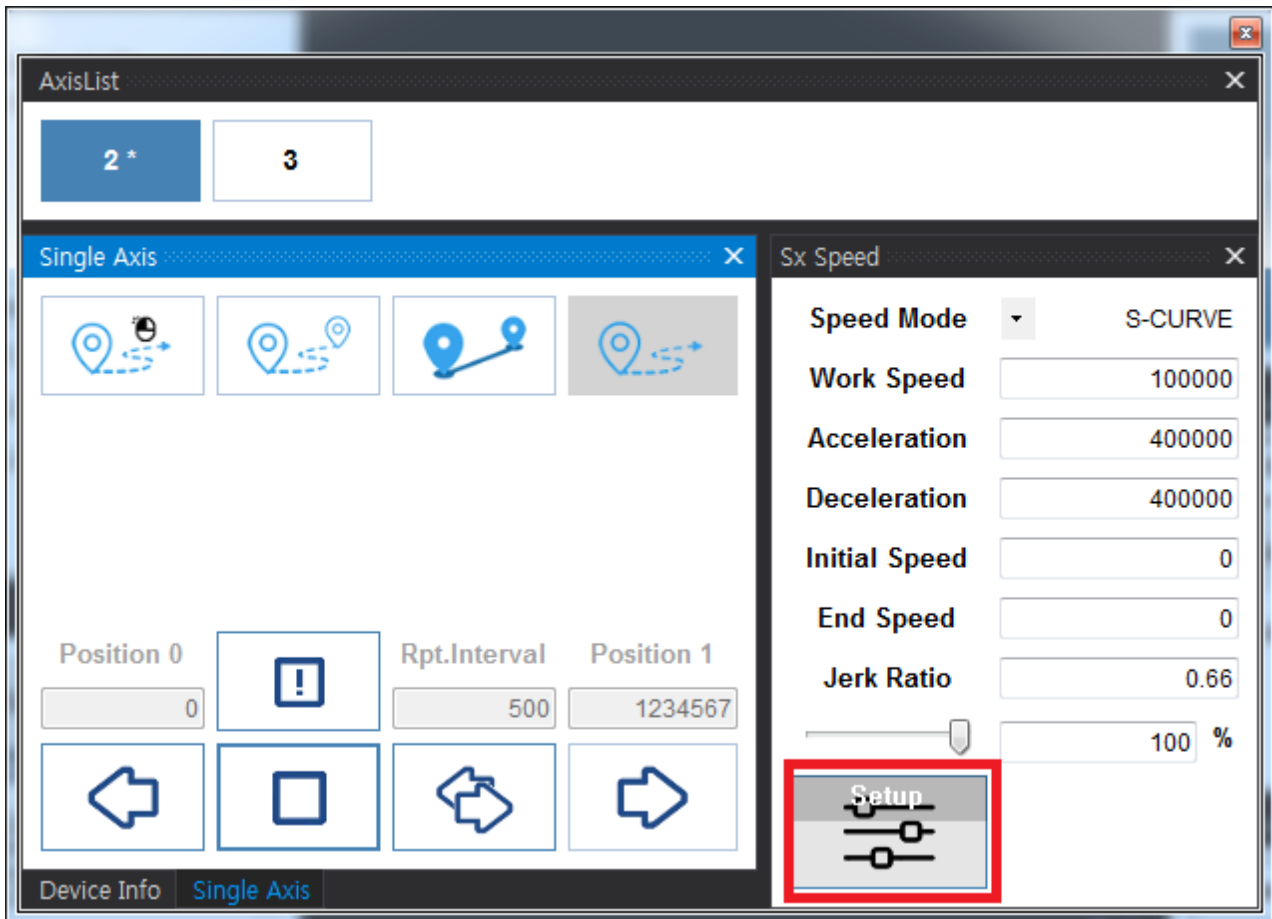
- AxisList



- AxisList
- AxisList

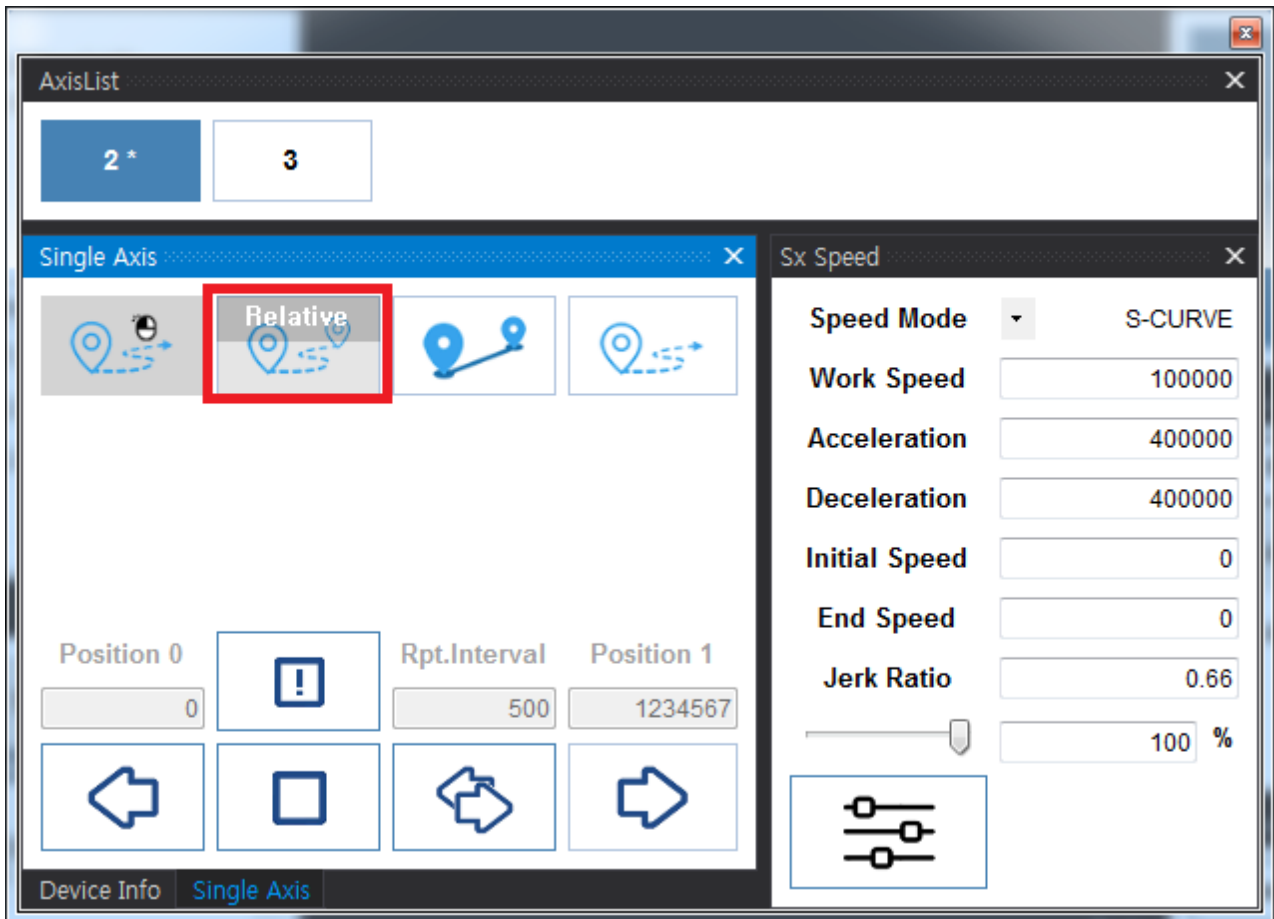


• 가 ,

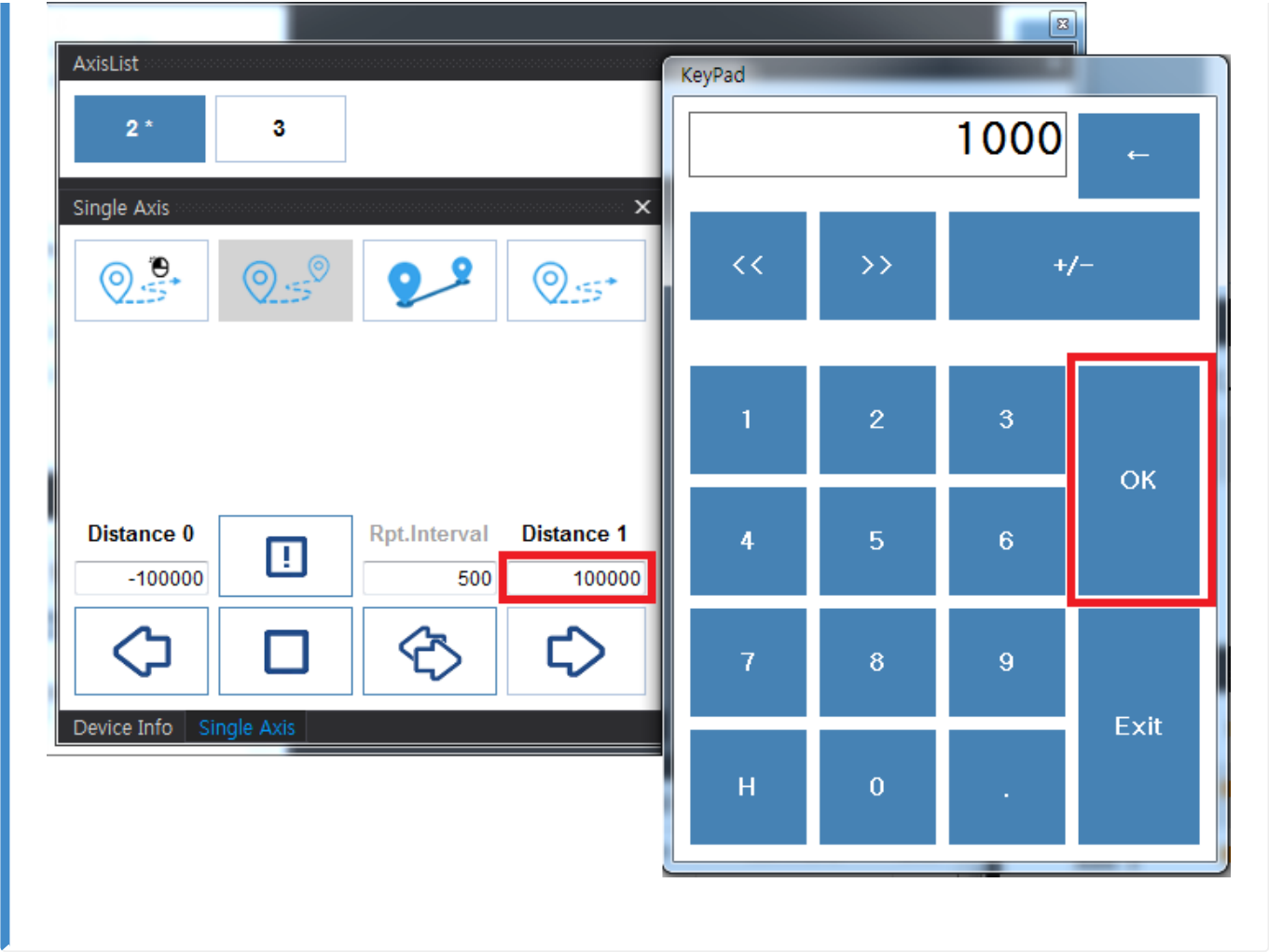


- Setup 가
- SetSpeed_Sx
- KeyPad KeyPad

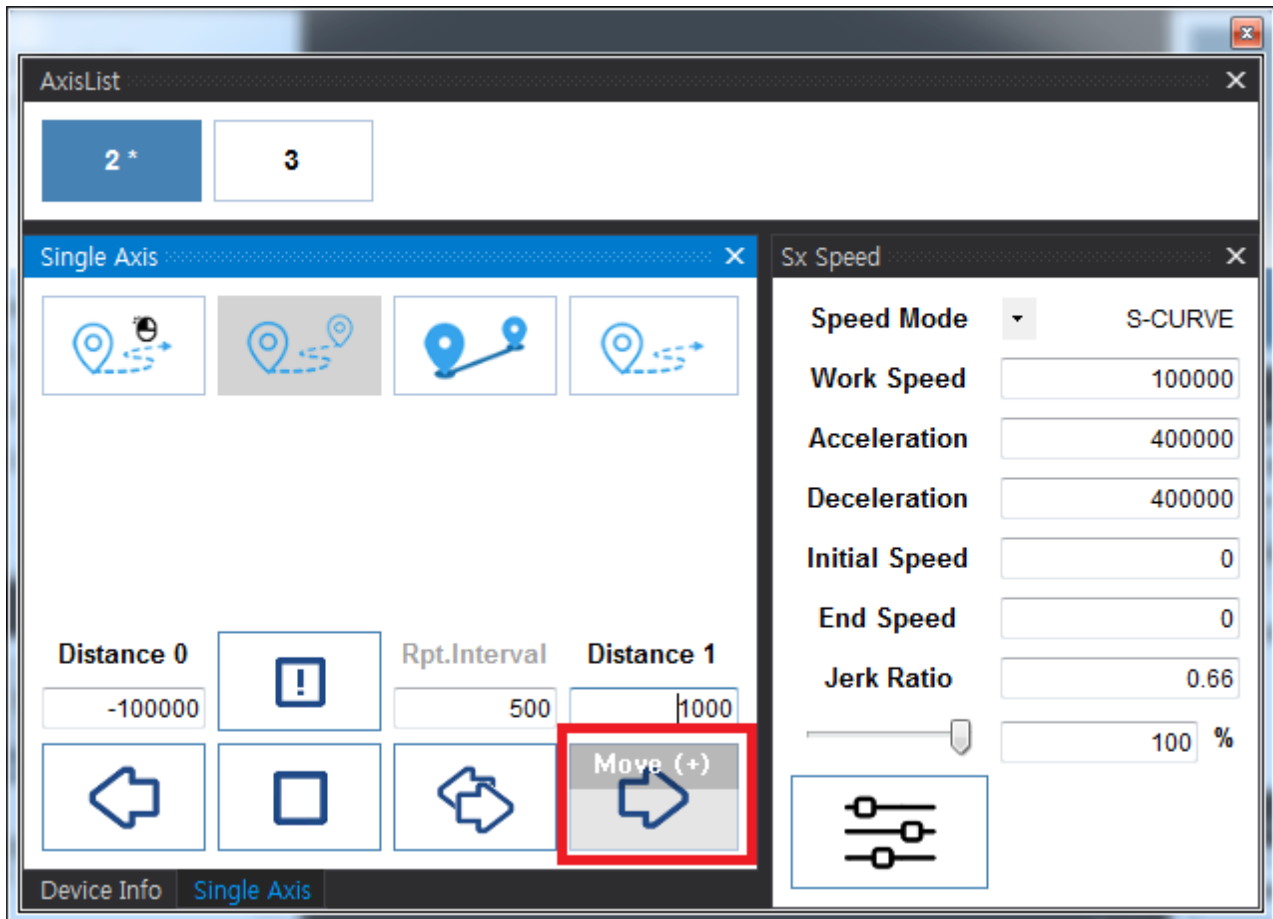
- 1) RelativeMove-Mode



- Distance



- Move
- **SingleAxis**



- Position Monitor

- Position Monitor

Reset	C.Position	F.Position	C.Speed	F.Speed	Torque
Axis 2	1 000	1 000	0	0	1.50
Axis 3	0	0	0	0	0.00

- Motor, Feedback Position 가

- [Trouble Shooting](#)

- **EtherCAT TroubleShooting**

- **PCI_Pulse TroubleShooting**
- **NEMO TroubleShooting**

1)

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Last update: **2024/07/08 18:23**