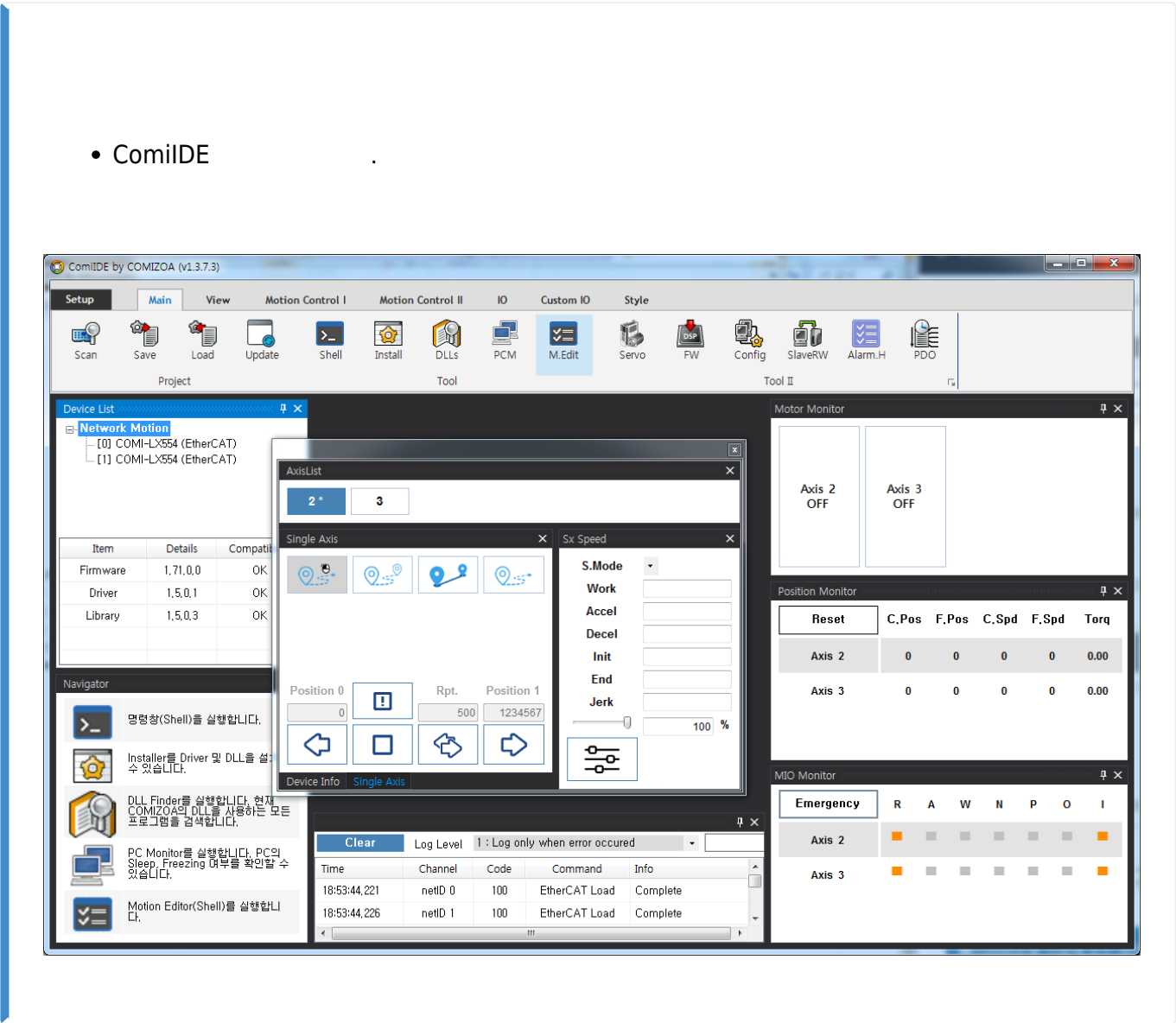


	1
	2
Servo On	3
Motor State	3
	4
	5
	7
	9
	11

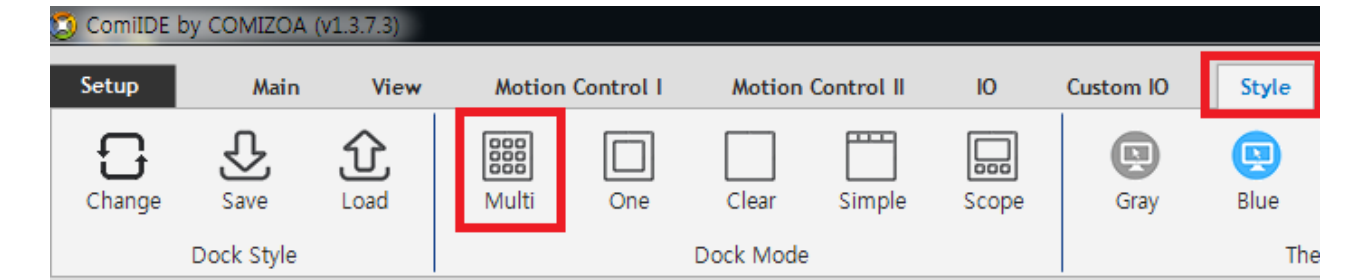
Motion Test

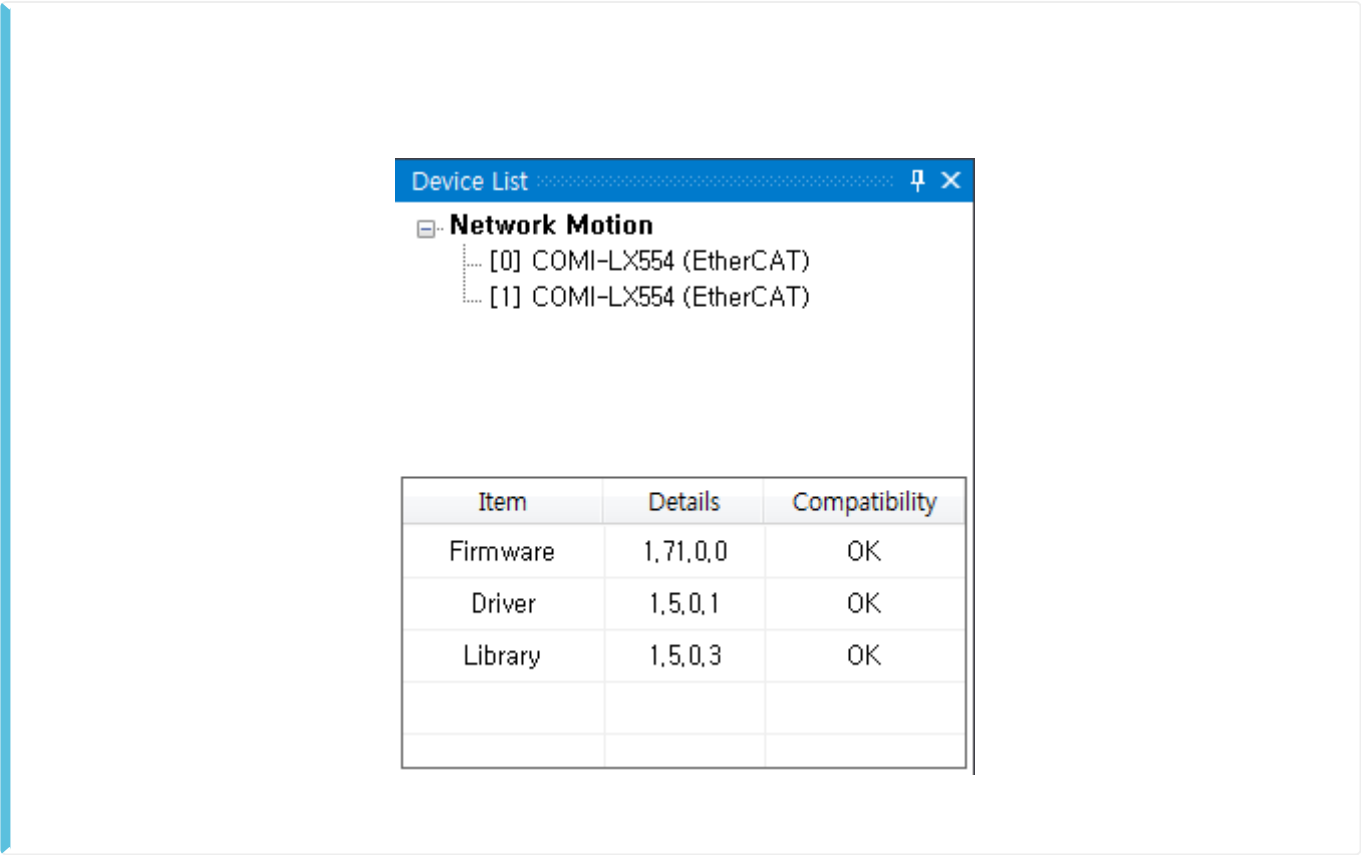
× ComiIDE

- ComiIDE



- , Style - Multi





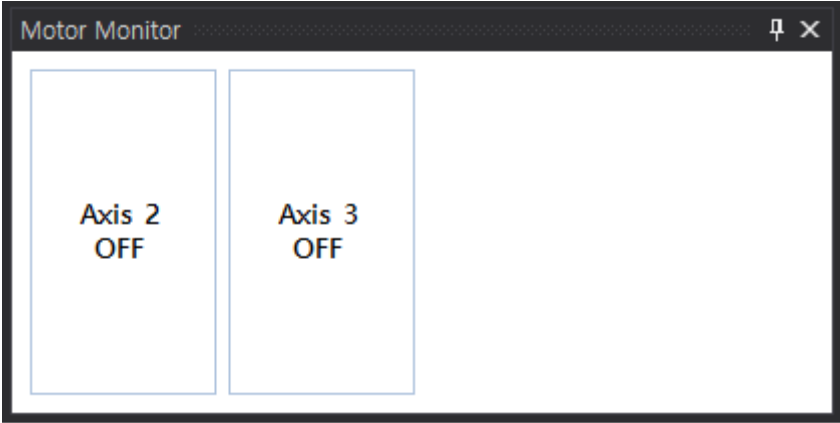
- DeviceList , Load .
- Device가 , .

Clear		Log Level 1 : Log only when error occurred			Find
Time	Channel	Code	Command	Info	
23:21:32,750	netID 0	100	EtherCAT Load	Complete	
23:21:32,773	netID 1	100	EtherCAT Load	Complete	

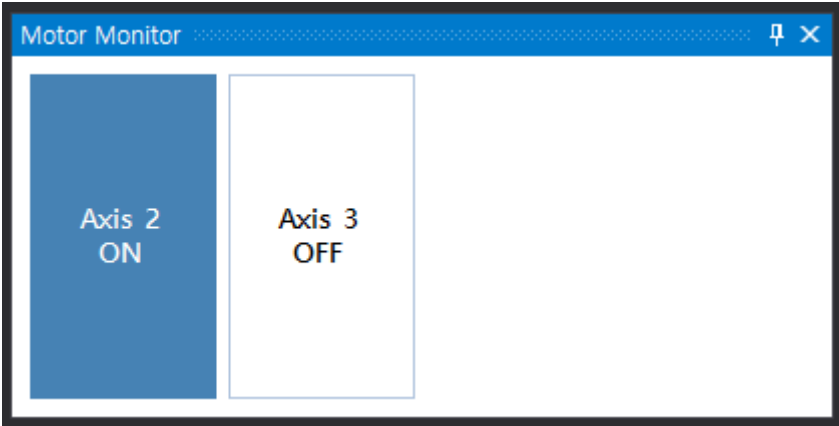
- LogView Load 가 .
- LogView Log View .

Servo On

- Motor Monitor 가 .



- Servo_On .



- Motor Monitor Motor ServoOn Stop .
- Motor Monitor **Motor Monitor** .

Motor State

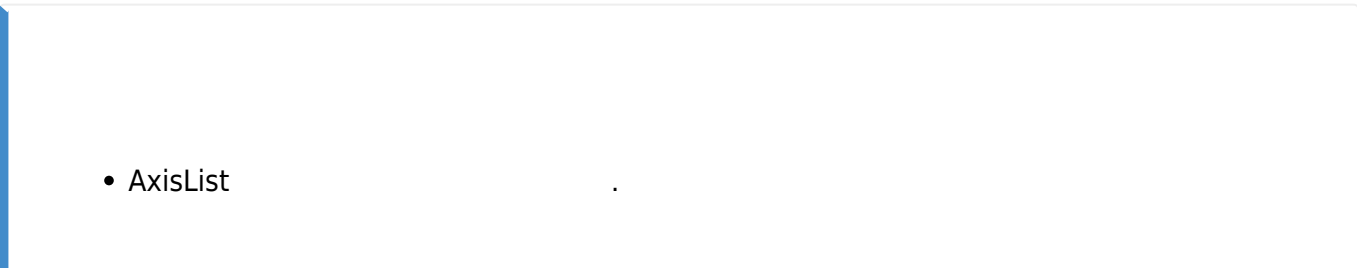
- Motor가 , .

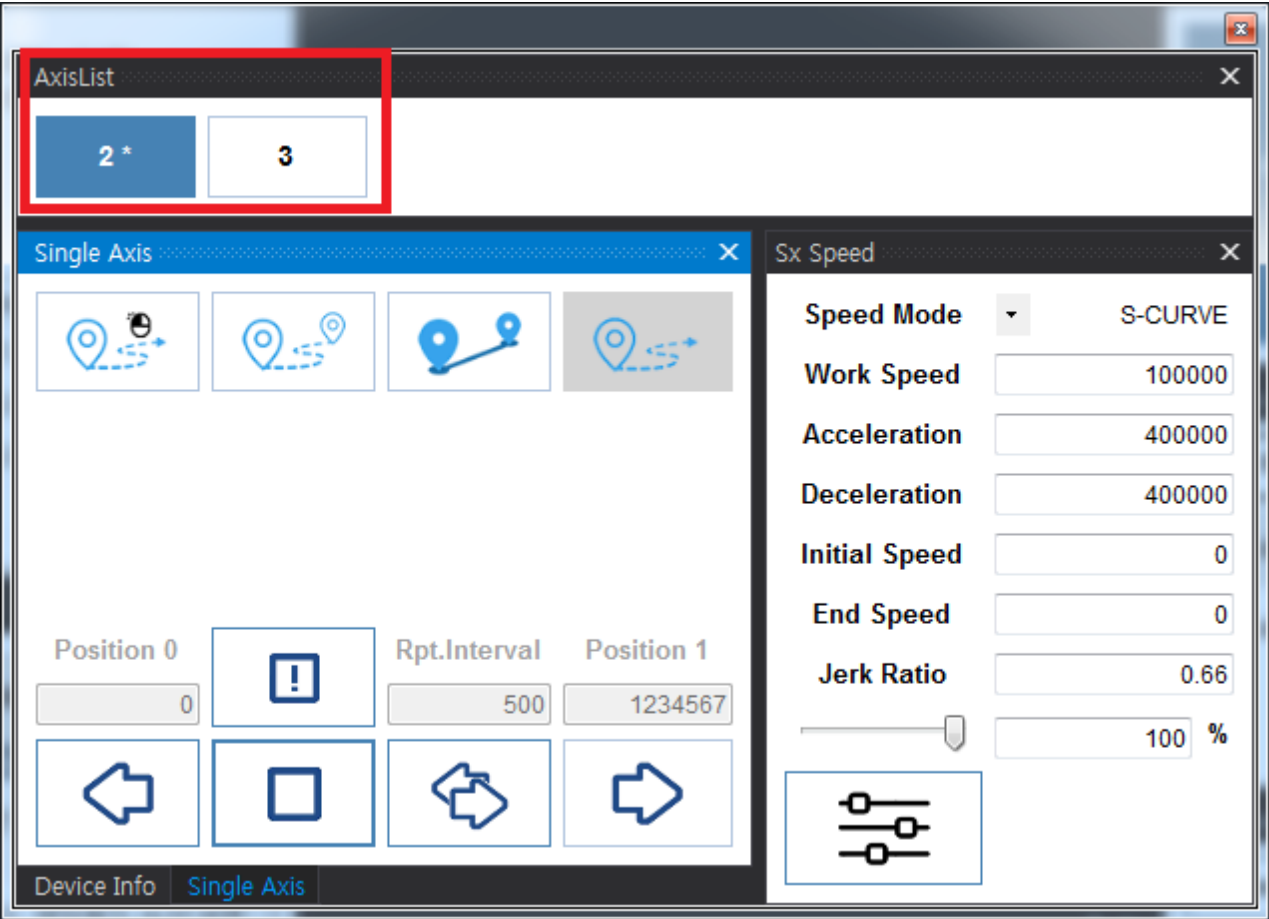


- Motor 가 Alarm , 가
- , Servo-On .
- MIO Monitor Motor가 가 .

MIO Monitor							
Emergency	RDY	ALM	WARN	NEL	PEL	ORG	INP
Axis 2							
Axis 3							

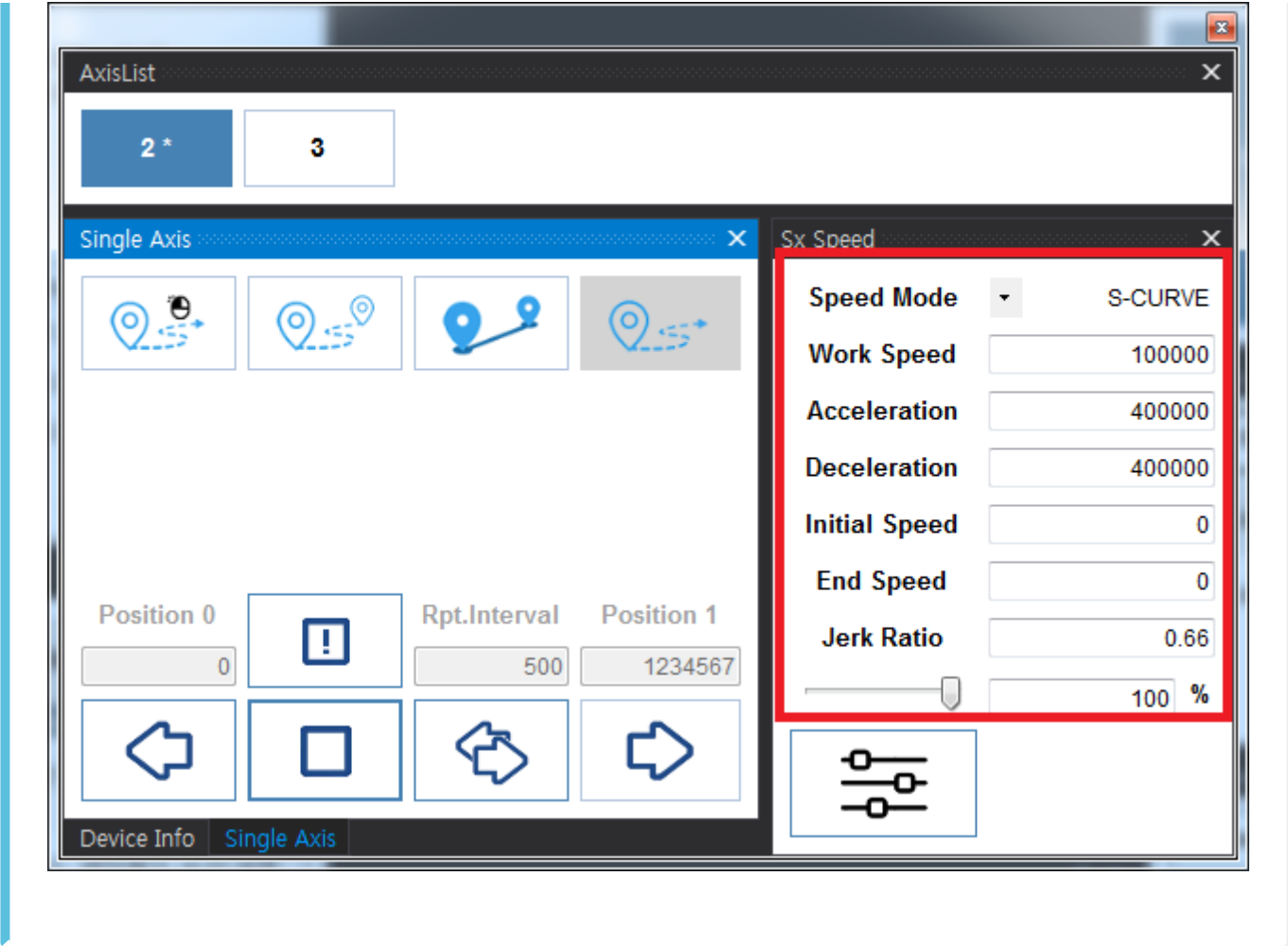
- , Alarm , PEL (Limit+) / NEL(Limit-) 가
- Ready , RDY 가 .
- MIO Monitor **MIO Monitor** .



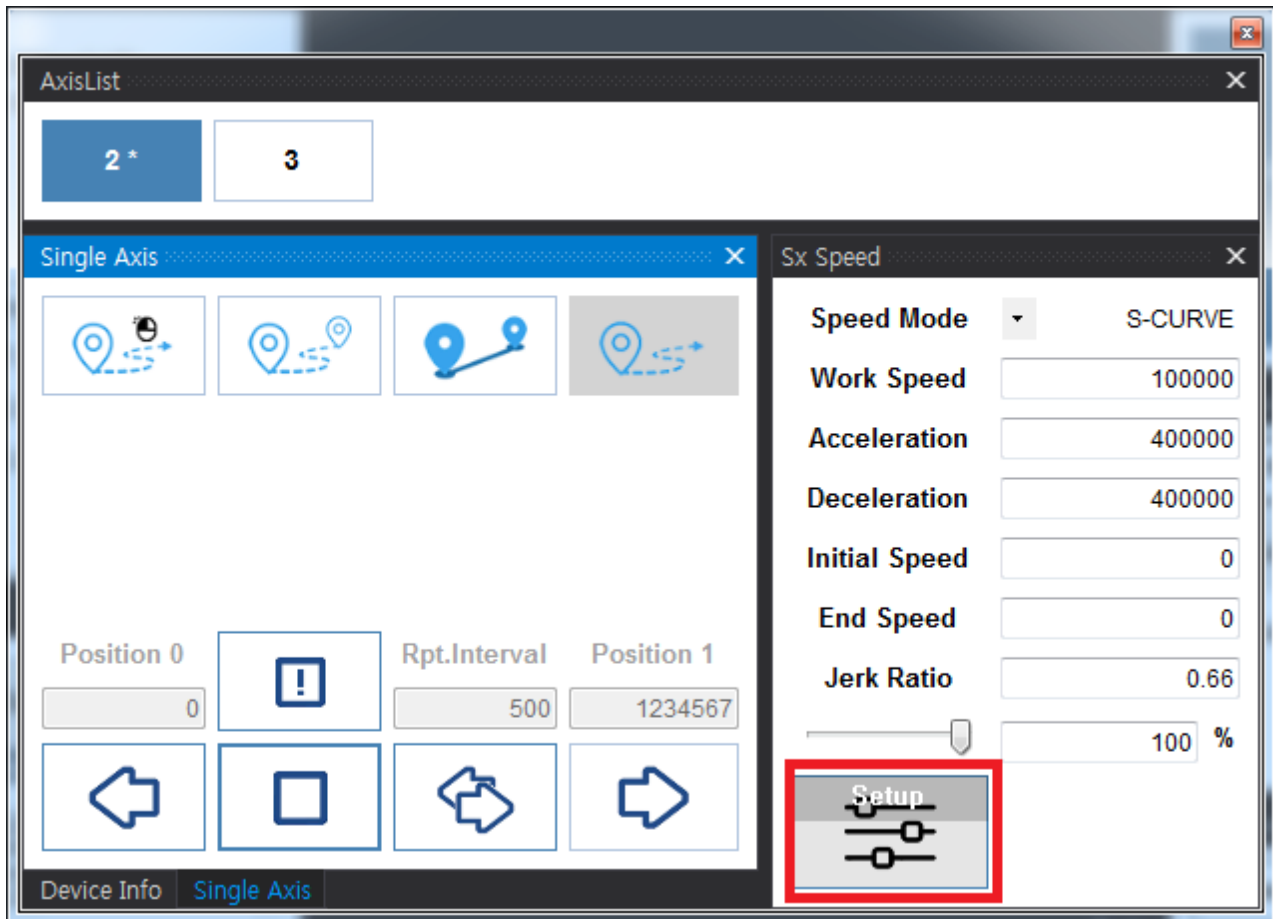


- AxisList

AxisList

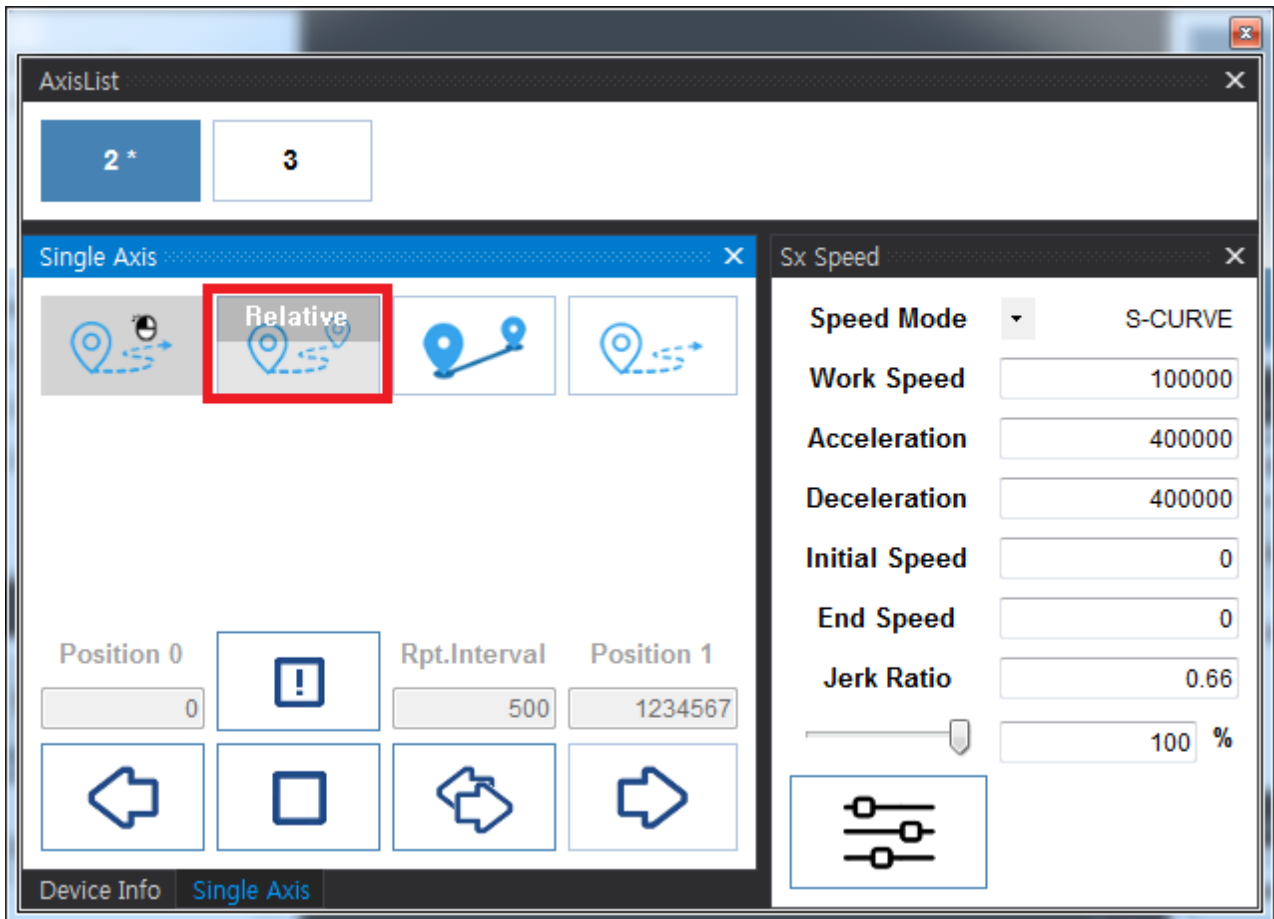


• 가 ,

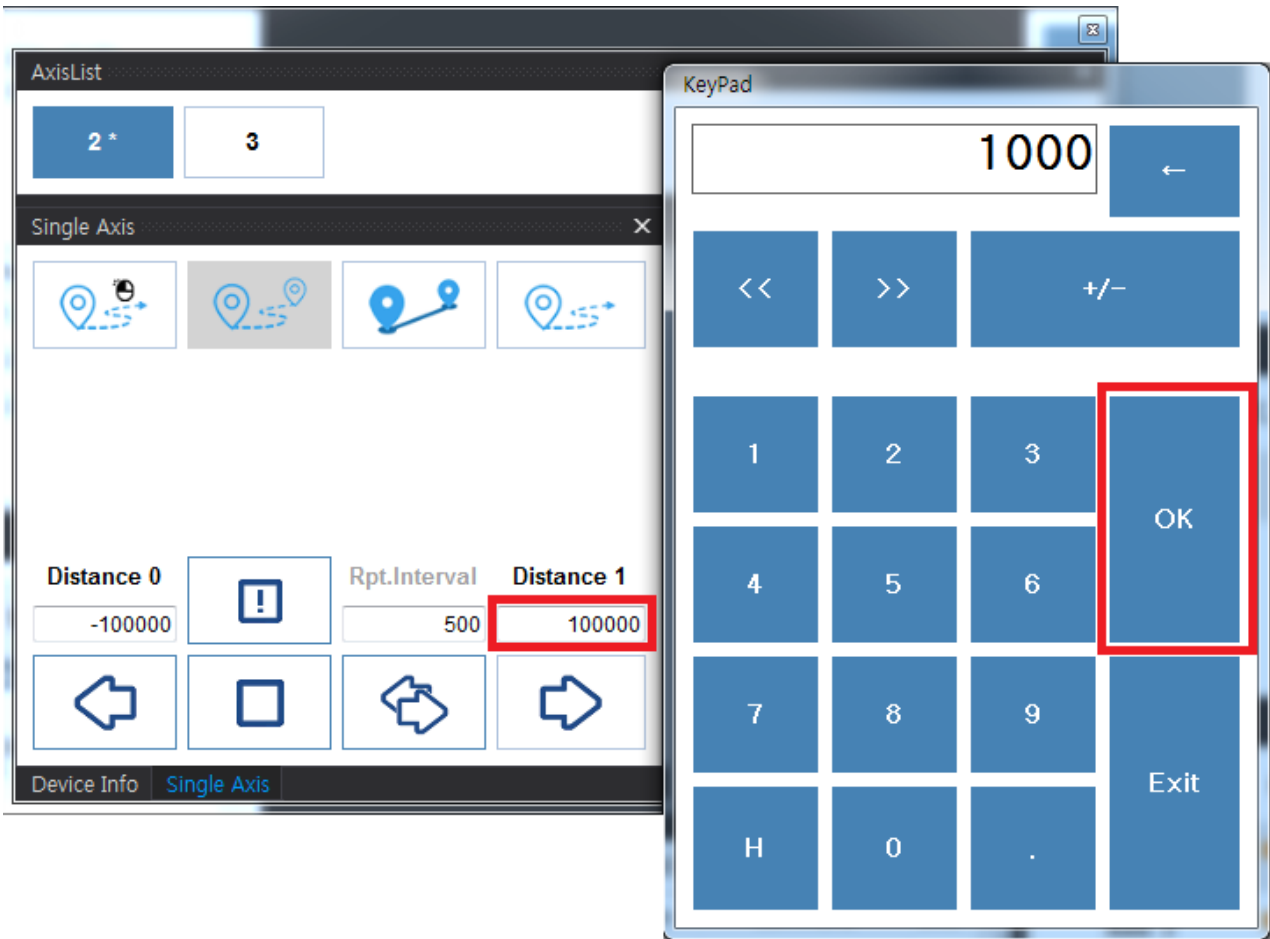


- Setup 가
- SetSpeed_Sx
- KeyPad KeyPad

- 1) RelativeMove-Mode



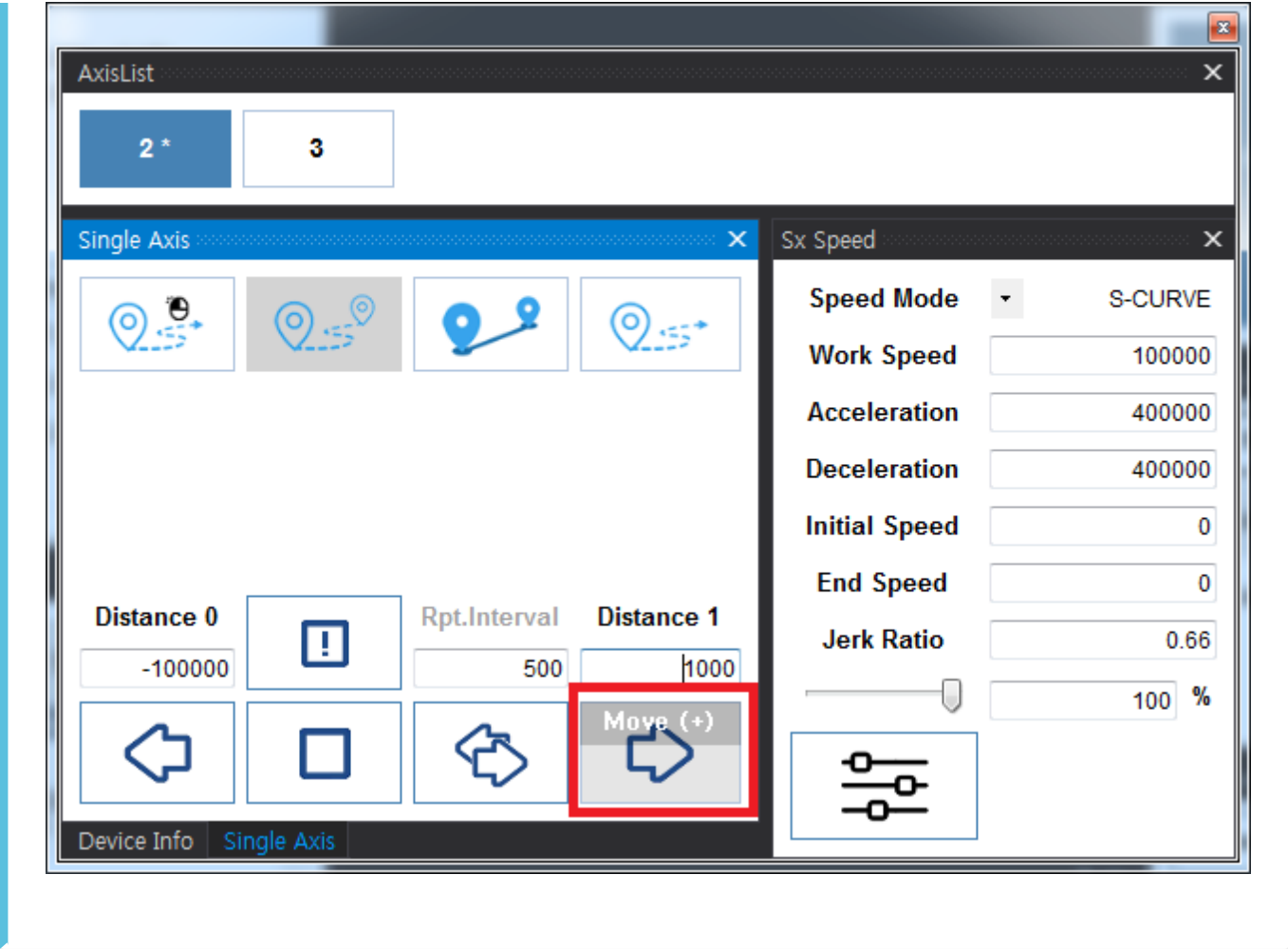
- Distance



- Move

-

SingleAxis



- Position Monitor Command Position Feedback Position
- Position Monitor **Position Monitor**

Position Monitor					
Reset	C.Position	F.Position	C.Speed	F.Speed	Torque
Axis 2	1 000	1 000	0	0	1.50
Axis 3	0	0	0	0	0.00

- Feedback Position ,
- Motor , 가 2)

Trouble Shooting

- [EtherCAT TroubleShooting](#)
- [PCI_Pulse TroubleShooting](#)
- [NEMO TroubleShooting](#)

1)

2)

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Last update: **2024/07/08 18:23**