

EtherCAT 1

 Initial AIState 1

 IO 1

 Software Emergency 1

EtherCAT

× EtherCAT Master 가

Initial AIState

- IDE , AIState
 - Initial : 'Initial'
 - Pre-OP : 'Pre-OP'
 - Safe-OP : 'Safe-OP'
 - OP : 'OP'
 - Don't Change :

×

- Setup ¹⁾ , Initial AIState 'OP' ' **EEPROM Read Failed**'

IO

- MotionIO Visible : , Driver MotionIO((EL, ORG)
IO
- Using LocalCh : LocalCh Master , Local

Software Emergency

- StopMode : Software Emergency 가
 - Emergency Stop :

1)

From:

<http://comizoa.co.kr/info/> - -

Permanent link:

http://comizoa.co.kr/info/doku.php?id=application:comiide:30_control:10_setup:60_ethercat

Last update: **2024/07/08 18:23**