

EtherCAT 1
 Initial AIState 1
 IO 1
 Software Emergency 1

EtherCAT

× EtherCAT Master 가

Initial AIState

- IDE , AIState
 - Initial : 'Initial'
 - Pre-OP : 'Pre-OP'
 - Safe-OP : 'Safe-OP'
 - OP : 'OP'
 - Don't Change :

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- Setup ¹⁾ , Initial AIState 'OP' ' **EEPROM Read Failed**'

IO

- MotionIO Visible : , Driver MotionIO((EL, ORG)
IO
- Using LocalCh : LocalCh Master , Local

Software Emergency

- StopMode : Software Emergency 가
◦ Emergency Stop :

1)

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