

.....	1
.....	1
Case 1	1
Case 2	2
Case 3	2
Case 4	2

x 가 .

(Cyclic Torque Mode) Target Torque 가 가 .

Case 1

- OutPDO Data Torque

- 1)

- OutPDO Data Torque 가 Configuration
 - Torque OutPDO Map

The screenshot shows the 'Configurator' software interface. At the top, there are buttons for Scan, Download, Upload, Save, Load, and Close. Below these are tabs for Topology, Net Info, Slave Info, and ProcessData (which is highlighted with a red box). The ProcessData tab contains several tables:

- SyncManager:** A table with columns SM, Size, and Type. Row 2 (SM 2) is highlighted in blue and labeled 'Outputs'.
- PDO List:** A table with columns Index, Size, Name, and SM. Row 2 (Index 0x1601) is highlighted in blue and labeled 'Receive PDO mapping 2'.
- PDO Assignment:** A table with columns Index and Type. Row 2 (Index 0x1601) is checked and highlighted with a red box.
- PDO Content (0x1A00):** A table with columns Index, Size, Name, and Type. Row 3 (Index 0x6071:00) is highlighted with a red box and labeled 'Target torque'.

At the bottom, there are buttons for Index and Addr, and a checkbox for 'Apply AutoAddress To Servo'.

- Config

Configuration Guide

- XML

. (OMRON xml)

- Torque Monitor가

Torque Monitor Failed

Case 2

-

- SDO 0x6080 (Max motor speed) 0 ²⁾

- SDO 0x6080 (Max motor speed)

- rpm

Case 3

-

- Pr0.00 0

-

- (Polarity) ³⁾ , 0x607E

- Pr0.00 0

Case 4

-

- Pr0.08 0
- **PANASONIC :**
- Pr0.08 0

1)

OutPDO Data

2)

Omron 0x607F (Max Profile Speed)

3)

No Reverse : 0 / Reverse : 224

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