

.....	1
.....	1
Case 1	1
Case 2	2
Case 3	2
Case 4	2

x 가 .

(Cyclic Torque Mode) Target Torque 가 가 .

Case 1

- OutPDO Data Torque
- 1)

- OutPDO Data Torque 가 Configuration
 - Torque OutPDO Map

The screenshot shows the 'Configurator' software interface. At the top, there are buttons for Scan, Download, Upload, Save, Load, and Close. Below these are tabs for Topology, Net Info, Slave Info, and ProcessData (which is highlighted with a red box). The ProcessData tab contains several tables:

- SyncManager:** A table with columns SM, Size, and Type. Row 2 is highlighted with a blue background and labeled 'Outputs'.
- PDO List:** A table with columns Index, Size, Name, and SM. Row 2 (Index 0x1601, Size 19, Name 'Receive PDO mapping 2', SM 2) is highlighted with a blue background and a red box.
- PDO Assignment:** A table with columns for Index and Name. Row 2 (Index 0x1601) is checked with a blue box and highlighted with a red box.
- PDO Content (0x1A00):** A table with columns Index, Size, Name, and Type. Row 3 (Index 0x6071:00, Size 2, Name 'Target torque', Type INT) is highlighted with a red box.

At the bottom, there are buttons for 'Index' and 'Addr', and a checkbox for 'Apply AutoAddress To Servo'.

- Config

Configuration Guide

- XML

. (OMRON xml)

- Torque Monitor가

Torque Monitor Failed

Case 2

-

- SDO 0x6080 (Max motor speed) 0 ²⁾

- SDO 0x6080 (Max motor speed)

- rpm

Case 3

-

- Pr0.00 0

-

- (Polarity) ³⁾ , 0x607E

- Pr0.00 0

Case 4

-

- Pr0.08 0
- **PANASONIC :**
- Pr0.08 0

1)

OutPDO Data

2)

Omron 0x607F (Max Profile Speed)

3)

No Reverse : 0 / Reverse : 224

From:

<http://comizoa.co.kr/info/> - -

Permanent link:

http://comizoa.co.kr/info/doku.php?id=platform:ethercat:70_users_guide:20_ts:torque_failed

Last update: **2024/07/08 18:23**