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, , torque, , ,

× 가 .

### Case 1

#### AddInfo

(Cyclic Torque Mode)

Target Torque

가

가

.

#### Cause

- OutPDO Data Torque

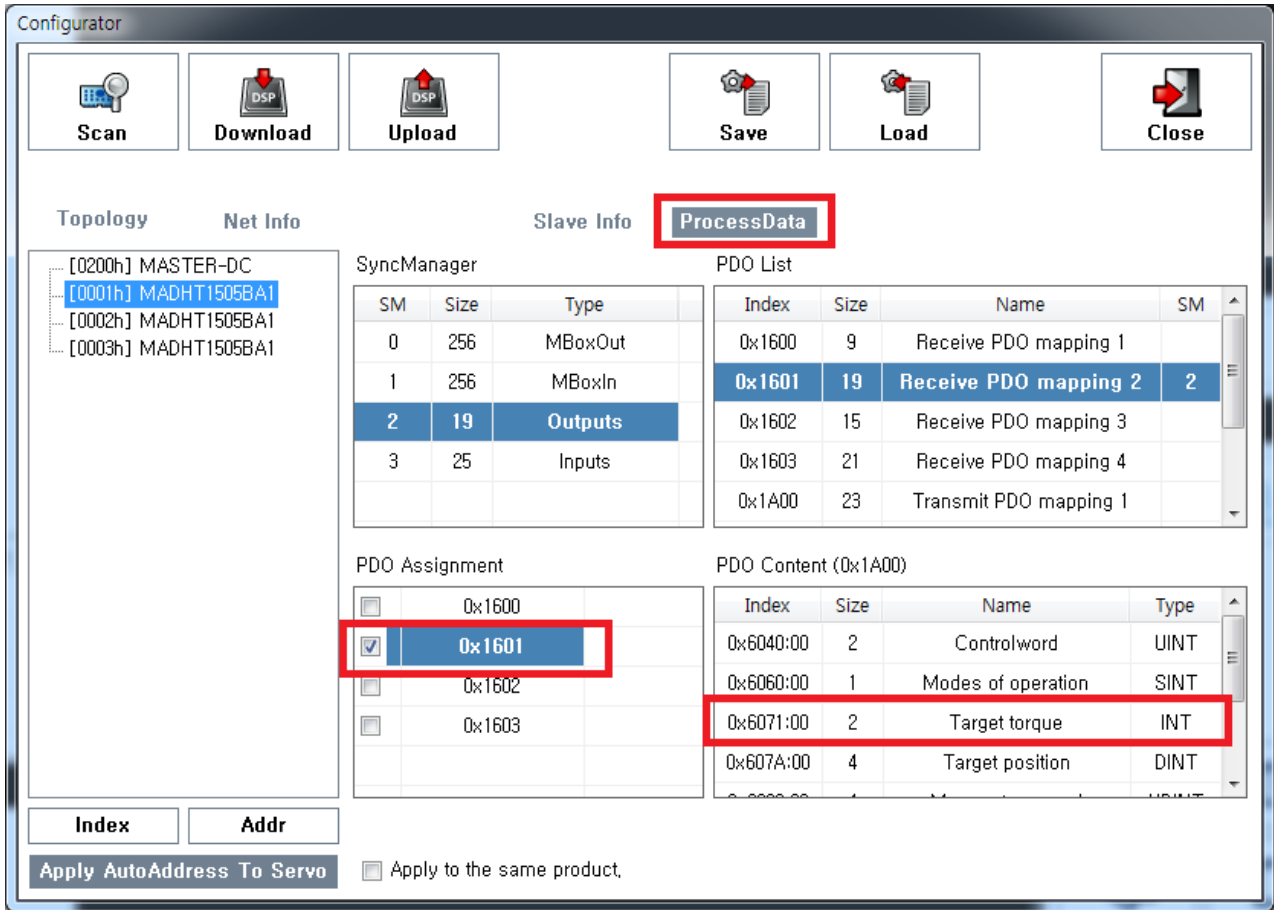
- 

1)

#### Solution

- OutPDO Data Torque
  - Torque

가 Configuration  
OutPDO Map



- Config

### Configuration Guide

- XML

. (OMRON xml )

- Torque Monitor가

### Torque Monitor Failed

×  
Config Info



## Case 2

### AddInfo

- 

### Cause

- SDO 0x6080 (Max motor speed) 0 2)

### Solution

- SDO 0x6080 (Max motor speed)
- rpm

## Case 3

### AddInfo

- 

### Cause

- Pr0.00 0
- 
- , 0x607E
- (Polarity)<sup>3)</sup>

### Solution

- Pr0.00 0

## Case 4

### AddInfo

- 

### Cause

- Pr0.08 0
- **PANASONIC :**

### Solution

- Pr0.08      0

1)

OutPDO Data

2)

Omron                      0x607F (Max Profile Speed)

3)

No Reverse : 0 / Reverse : 224

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