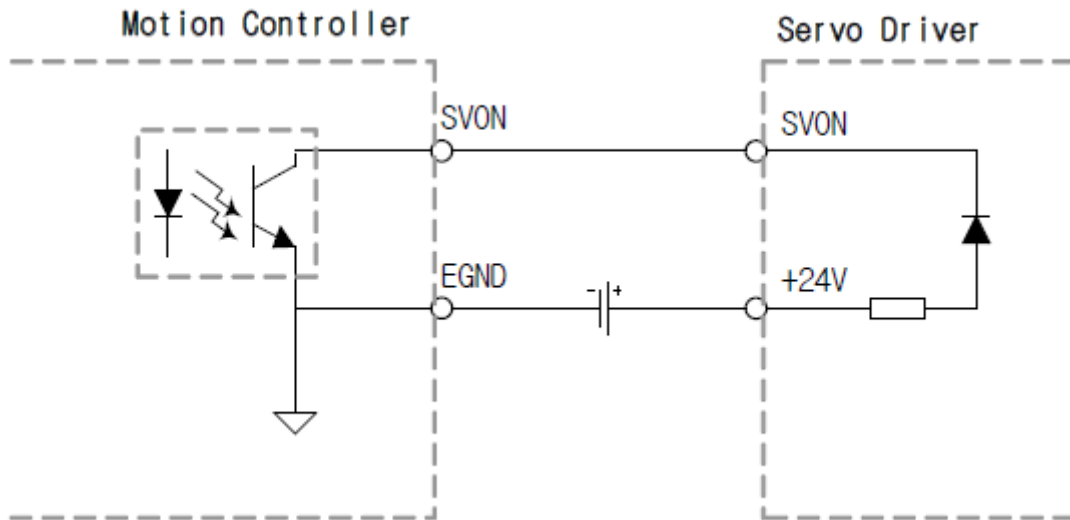


SVON (Servo-On)	1
RDY (Ready)	1
ALM (ALARM)	2
INP (In-position)	3

x

SVON (Servo-On)

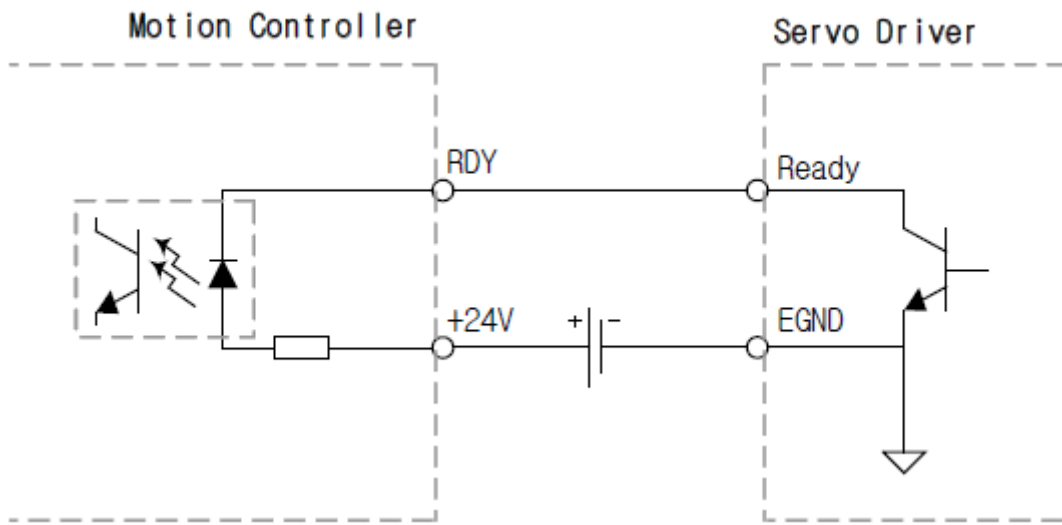
- ON/OFF
SERVO-ON
- `cmmGnSetServoOn()` SERVO ON/OFF
SERVO-ON
- SVON



RDY (Ready)

- RDY 가 SERVON-ON 가
- 가 SERVO-ON
- `cmmStReadMioStatuses()` BIT0 RDY

- RDY



ALM (ALARM)

- ALM

ALARM

- ALM 가 ON

- ALM ALM (,)

- ALM

Basic I/O Setup

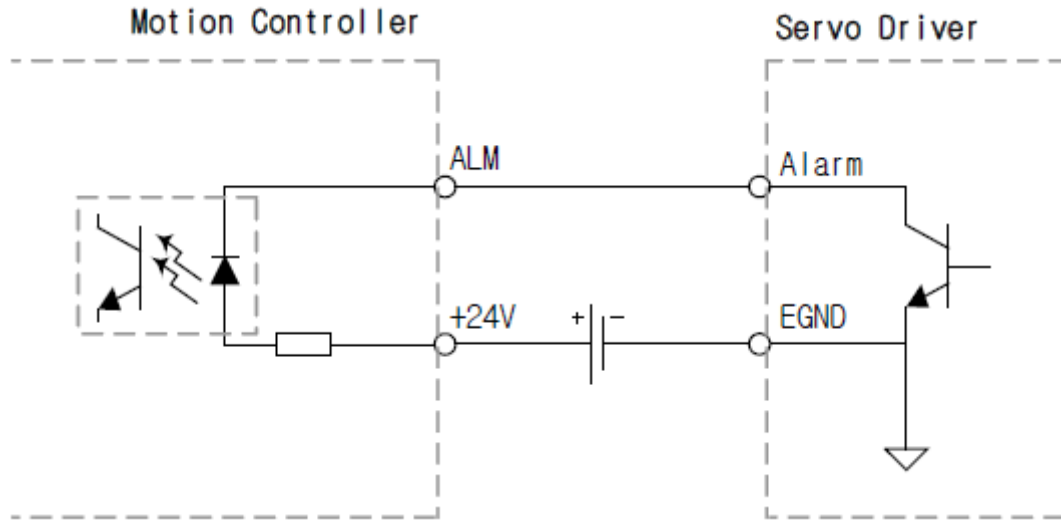
Application

cmmCfgSetMioProperty

- ALM 가 ON

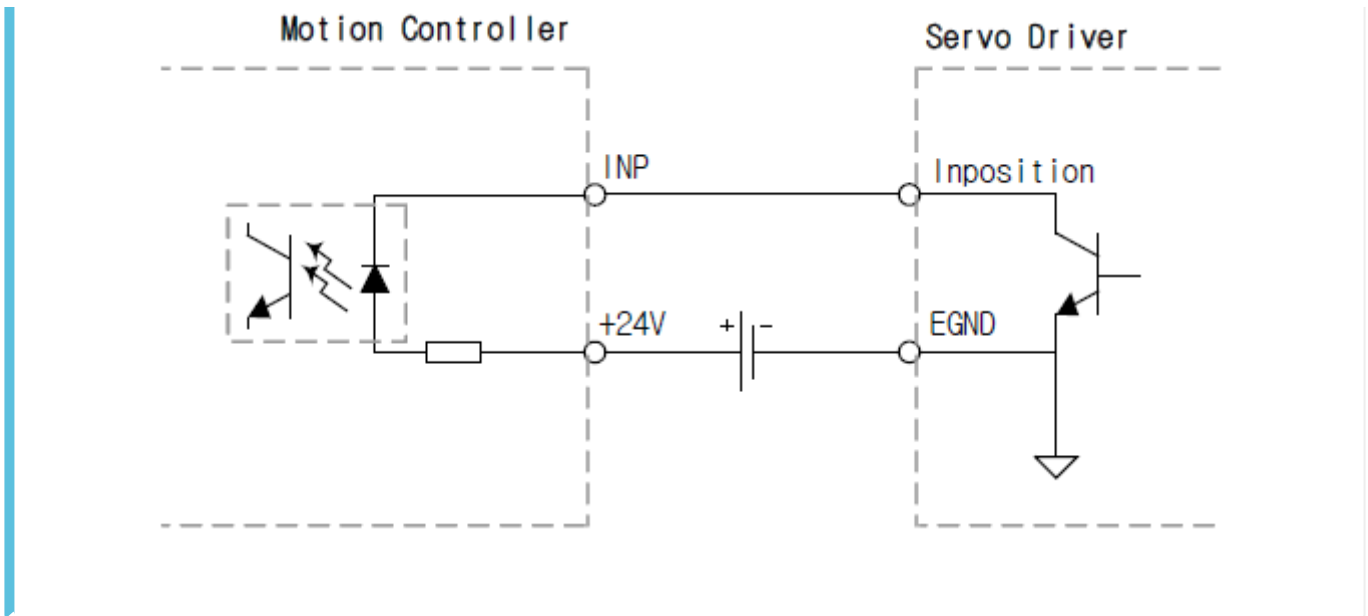
ALM ALM B
(Normal Close)

- ALM ALM B ALM
GND



INP (In-position)

- INP (Deviation counter) Inposition-range ,
- 가 가
- ¹⁾ 0 0
- INP Inposition-range ON , OFF가
- Inposition-range MITSUBISHI Param No.5 "In-position range"



- COMMAND
- INP (Enable) COMMAND
- INP 가 ON
- INP INP 가 ON
- INP INP 가 INP
- INP / Application Basic I/O Setup
 , cmmCfgSetMioProperty

1) (Deviation counter) (Command pulse) (Feedback pulse)

From:
<http://comizoa.co.kr/info/> - -
 Permanent link:
http://comizoa.co.kr/info/doku.php?id=platform:pulse:info:interface:servo_signal&rev=1547185940
 Last update: **2024/07/08 18:22**