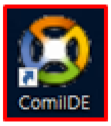
목차

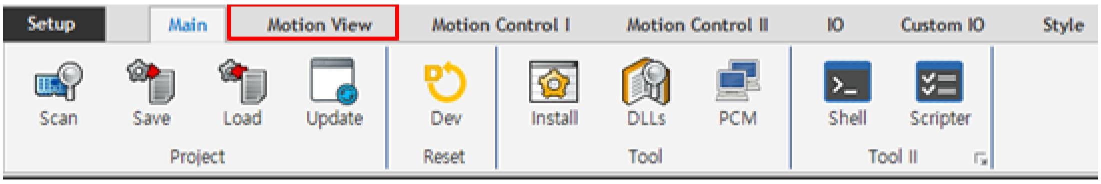
DLL_Logger 사용법

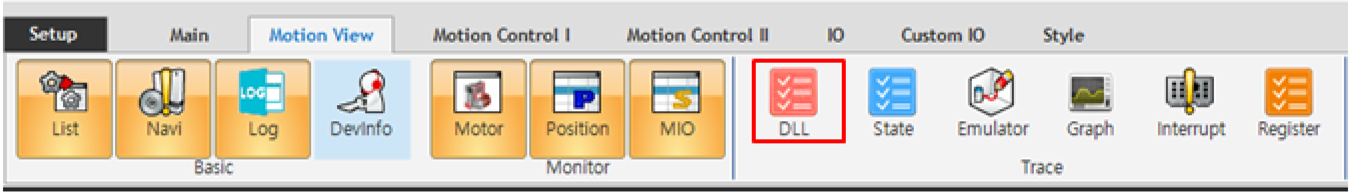
× DLL_Logger 사용법 방법에 대한 안내 페이지입니다.

- 자체적으로 개발한 프로그램이 제대로 실행 되지 않을때 문제점을 파악하기 위함입니다.

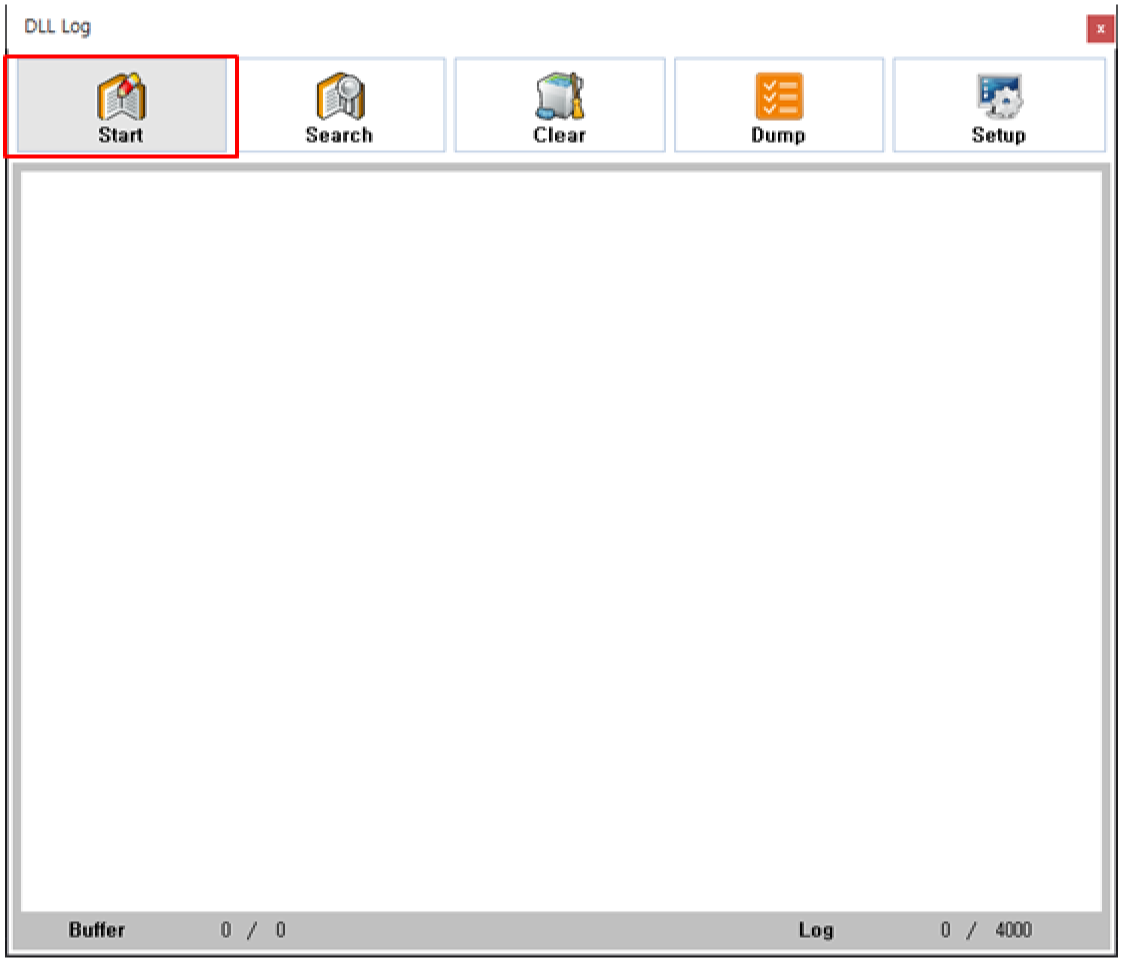
1 Comiide.exe 를 실행합니다.



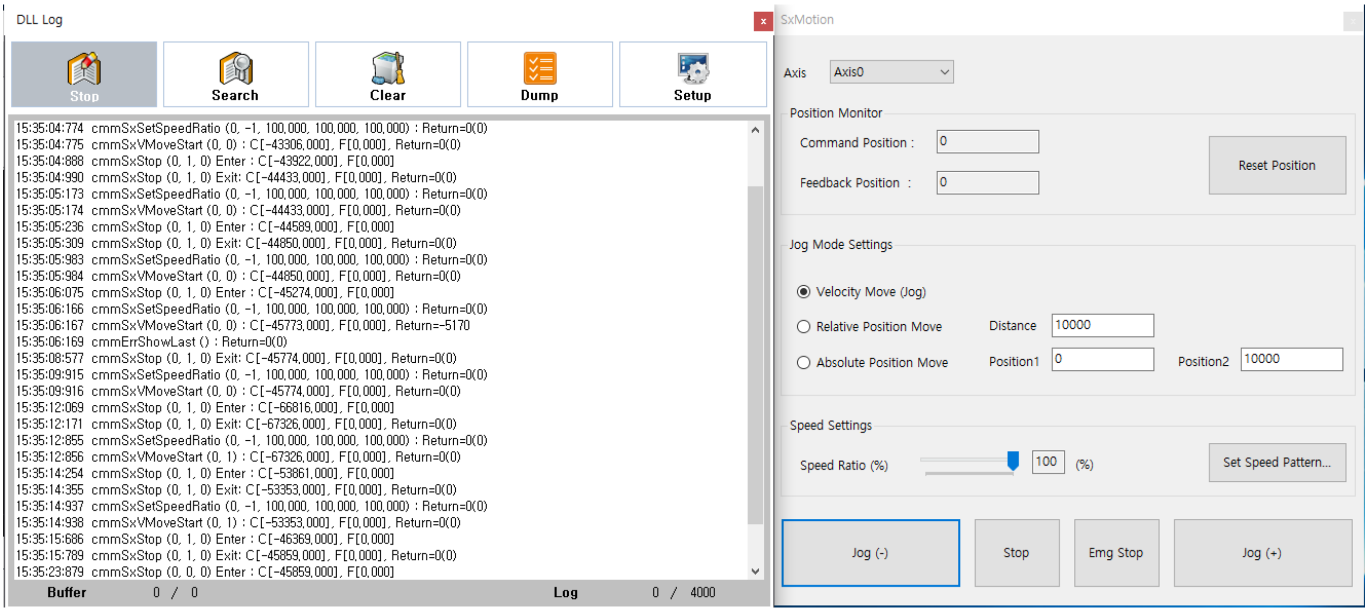

Setup
Main
Motion View
Motion Control I
Motion Control II
IO
Custom IO
Style
Scan
Save
Load
Update
Project
Dev
Reset
Install
DLLs
PCM
Tool
Shell
Scripter
Tool II


Setup
Main
Motion View
Motion Control I
Motion Control II
IO
Custom IO
Style
List
Navi
Log
DevInfo
Basic
Motor
Position
MIO
Monitor
DLL
State
Emulator
Graph
Interrupt
Register
Trace

- 그 다음 왼쪽 상단 메뉴바 에서 Motion view 를 선택한후 DLL을 클릭합니다.



- Start를 눌러 DLL_Logger를 실행 시킨후 개발 프로그램을 실행합니다.



```
15:35:04:774  cmmSxSetSpeedRatio (0, -1, 100,000, 100,000, 100,000) : Return=0(0)
15:35:04:775  cmmSxVMoveStart (0, 0) : C[-43306,000], F[0,000], Return=0(0)
15:35:04:888  cmmSxStop (0, 1, 0) Enter : C[-43922,000], F[0,000]
15:35:04:990  cmmSxStop (0, 1, 0) Exit: C[-44433,000], F[0,000], Return=0(0)
15:35:05:173  cmmSxSetSpeedRatio (0, -1, 100,000, 100,000, 100,000) : Return=0(0)
15:35:05:174  cmmSxVMoveStart (0, 0) : C[-44433,000], F[0,000], Return=0(0)
15:35:05:236  cmmSxStop (0, 1, 0) Enter : C[-44589,000], F[0,000]
15:35:05:309  cmmSxStop (0, 1, 0) Exit: C[-44850,000], F[0,000], Return=0(0)
15:35:05:983  cmmSxSetSpeedRatio (0, -1, 100,000, 100,000, 100,000) : Return=0(0)
15:35:05:984  cmmSxVMoveStart (0, 0) : C[-44850,000], F[0,000], Return=0(0)
15:35:06:075  cmmSxStop (0, 1, 0) Enter : C[-45274,000], F[0,000]
15:35:06:166  cmmSxSetSpeedRatio (0, -1, 100,000, 100,000, 100,000) : Return=0(0)
15:35:06:167  cmmSxVMoveStart (0, 0) : C[-45773,000], F[0,000], Return=-5170
15:35:06:169  cmmErrShowLast () : Return=0(0)
15:35:08:577  cmmSxStop (0, 1, 0) Exit: C[-45774,000], F[0,000], Return=0(0)
15:35:09:915  cmmSxSetSpeedRatio (0, -1, 100,000, 100,000, 100,000) : Return=0(0)
15:35:09:916  cmmSxVMoveStart (0, 0) : C[-45774,000], F[0,000], Return=0(0)
15:35:12:069  cmmSxStop (0, 1, 0) Enter : C[-66816,000], F[0,000]
15:35:12:171  cmmSxStop (0, 1, 0) Exit: C[-67326,000], F[0,000], Return=0(0)
15:35:12:855  cmmSxSetSpeedRatio (0, -1, 100,000, 100,000, 100,000) : Return=0(0)
15:35:12:856  cmmSxVMoveStart (0, 1) : C[-67326,000], F[0,000], Return=0(0)
15:35:14:254  cmmSxStop (0, 1, 0) Enter : C[-53861,000], F[0,000]
15:35:14:355  cmmSxStop (0, 1, 0) Exit: C[-53353,000], F[0,000], Return=0(0)
15:35:14:937  cmmSxSetSpeedRatio (0, -1, 100,000, 100,000, 100,000) : Return=0(0)
15:35:14:938  cmmSxVMoveStart (0, 1) : C[-53353,000], F[0,000], Return=0(0)
15:35:15:686  cmmSxStop (0, 1, 0) Enter : C[-46369,000], F[0,000]
15:35:15:789  cmmSxStop (0, 1, 0) Exit: C[-45859,000], F[0,000], Return=0(0)
15:35:23:879  cmmSxStop (0, 0, 0) Enter : C[-45859,000], F[0,000]
```

Buffer 0 / 0   Log 0 / 4000

Axis: Axis0

Position Monitor
Command Position : 0
Feedback Position : 0

Jog Mode Settings
● Velocity Move (Jog)
○ Relative Position Move   Distance 10000
○ Absolute Position Move   Position1 0   Position2 10000

Speed Settings
Speed Ratio (%) 100 (%)

- 그다음 개발 프로그램에서 명령을 내려 DLL_Logger에 뜨는 로그를 보고 문제점을 파악합니다.

From:
http://comizoa.co.kr/info/ - **-**

Permanent link:
http://comizoa.co.kr/info/doku.php?id=practice:dll_logger_%EC%82%AC%EC%9A%A9%EB%B2%95&rev=1625639880

Last update: **2024/07/08 18:23**